# R&S®NRP-Zxx Power Sensors Specifications









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## **Definitions**

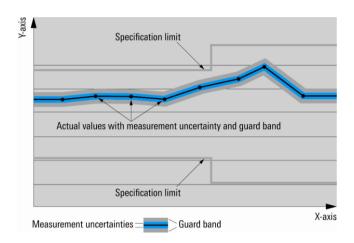
#### General

Product data applies under the following conditions:

- · Three hours storage at ambient temperature followed by 30 minutes warm-up operation
- Specified environmental conditions met
- · Recommended calibration interval adhered to
- · All internal automatic adjustments performed, if applicable

#### Specifications with limits

Represent warranted product performance by means of a range of values for the specified parameter. These specifications are marked with limiting symbols such as  $\langle , \leq , > , \geq , \pm \rangle$ , or descriptions such as maximum, limit of, minimum. Compliance is ensured by testing or is derived from the design. Test limits are narrowed by guard bands to take into account measurement uncertainties, drift and aging, if applicable.



#### Specifications without limits

Represent warranted product performance for the specified parameter. These specifications are not specially marked and represent values with no or negligible deviations from the given value (e.g. dimensions or resolution of a setting parameter). Compliance is ensured by design.

#### Typical data (typ.)

Characterizes product performance by means of representative information for the given parameter. When marked with <, > or as a range, it represents the performance met by approximately 80 % of the instruments at production time. Otherwise, it represents the mean value.

#### Nominal values (nom.)

Characterize product performance by means of a representative value for the given parameter (e.g. nominal impedance). In contrast to typical data, a statistical evaluation does not take place and the parameter is not tested during production.

#### Measured values (meas.)

Characterize expected product performance by means of measurement results gained from individual samples.

#### **Uncertainties**

Represent limits of measurement uncertainty for a given measurand. Uncertainty is defined with a coverage factor of 2 and has been calculated in line with the rules of the Guide to the Expression of Uncertainty in Measurement (GUM), taking into account environmental conditions, aging, wear and tear.

Device settings and GUI parameters are indicated as follows: "parameter: value".

Typical data as well as nominal and measured values are not warranted by Rohde & Schwarz.

In line with the 3GPP/3GPP2 standard, chip rates are specified in Mcps (million chips per second), whereas bit rates and symbol rates are specified in Mbps (million bits per second), kbps (thousand bits per second), Msps (million symbols per second) or ksps (thousand symbols per second), and sample rates are specified in Msample/s (million samples per second). Mcps, Mbps, Msps, ksps and Msample/s are not SI units.

# Overview of the R&S®NRP-Zxx power sensors

Sensor type	Frequency range	Power range,	Connector type
R&S®		max. average power / peak envelope power	
Two-path diode pe	ower sensors		
NRP-Z211	10 MHz to 8 GHz	1.0 nW to 100 mW (-60 dBm to +20 dBm)	N
		max. 400 mW (AVG) / 2 W (PK, 10 μs)	
NRP-Z221	10 MHz to 18 GHz	1.0 nW to 100 mW (-60 dBm to +20 dBm)	N
		max. 400 mW (AVG) / 2 W (PK, 10 μs)	
Wideband power	sensors		·
NRP-Z81	50 MHz to 18 GHz	1 nW to 100 mW (-60 dBm to +20 dBm)	N
		max. 200 mW (AVG) / 1 W (PK, 1 µs)	
NRP-Z85	50 MHz to 40 GHz	1 nW to 100 mW (-60 dBm to +20 dBm)	2.92 mm
		max. 200 mW (AVG) / 1 W (PK, 1 µs)	
NRP-Z86	50 MHz to 40 GHz	1 nW to 100 mW (-60 dBm to +20 dBm)	2.40 mm
model .40		max. 200 mW (AVG) / 1 W (PK, 1 µs)	
NRP-Z86	50 MHz to 44 GHz	1 nW to 100 mW (-60 dBm to +20 dBm)	2.40 mm
model .44		max. 200 mW (AVG) / 1 W (PK, 1 µs)	
Level control sens	sors		
NRP-Z28	10 MHz to 18 GHz	200 pW to 100 mW (-67 dBm to +20 dBm)	N
		max. 700 mW (AVG) / 4 W (PK, 10 μs)	
NRP-Z98	9 kHz to 6 GHz	200 pW to 100 mW (-67 dBm to +20 dBm)	N
		max. 700 mW (AVG) / 4 W (PK, 10 μs)	
Power sensor mo	dules		
NRP-Z27	DC to 18 GHz	4 μW to 400 mW (–24 dBm to +26 dBm)	N
		max. 500 mW (AVG) / 30 W (PK, 1 μs)	
NRP-Z37	DC to 26.5 GHz	4 μW to 400 mW (–24 dBm to +26 dBm)	3.5 mm
		max. 500 mW (AVG) / 30 W (PK, 1 μs)	

# Specifications in brief of the R&S®NRP-Zxx power sensors

Sensor type	Impedance matching (SWR)			Noise (typ.)	Uncertainty for power measurements at +20 °C to +25 °C	
R&S®			(typ.)	().	absolute	relative
Two-path diod	le power sensors					
NRP-Z211	10 MHz to 2.4 GHz: < 1.13				0.054 dB to	0.022 dB to
	> 2.4 GHz to 8.0 GHz: < 1.20	< 10 µs			0.110 dB	0.112 dB
NRP-Z221	10 MHz to 2.4 GHz: < 1.13	> 40 kHz	290 pW	180 pW	0.054 dB to	0.022 dB to
	> 2.4 GHz to 8.0 GHz: < 1.20		·		0.143 dB	0.142 dB
	> 8.0 GHz to 18.0 GHz: < 1.25					
Wideband pov	ver sensors					
NRP-Z81	50 MHz to 2.4 GHz: < 1.16				0.130 dB to	0.039 dB to
	> 2.4 GHz to 8.0 GHz: < 1.20				0.150 dB	0.148 dB
	> 8.0 GHz to 18.0 GHz: < 1.25					
NRP-Z85	50 MHz to 2.4 GHz: < 1.16				0.130 dB to	0.039 dB to
	> 2.4 GHz to 8.0 GHz: < 1.20				0.170 dB	0.165 dB
NRP-Z86	> 8.0 GHz to 18.0 GHz: < 1.25					
model .40	> 18.0 GHz to 26.5 GHz:< 1.30	< 13 ns	220 pW	110 pW		
	> 26.5 GHz to 40.0 GHz:< 1.35	> 30 MHz				
NRP-Z86	50 MHz to 2.4 GHz: < 1.16				0.130 dB to	0.039 dB to
model .44	> 2.4 GHz to 8.0 GHz: < 1.20				0.190 dB	0.165 dB
	> 8.0 GHz to 18.0 GHz: < 1.25					
	> 18.0 GHz to 26.5 GHz:< 1.30					
	> 26.5 GHz to 40.0 GHz:< 1.35					
	> 40.0 GHz to 44.0 GHz:< 1.40					
Level control :						
NRP-Z28	10 MHz to 2.4 GHz: < 1.11	< 8 µs			0.047 dB to	0.022 dB to
	> 2.4 GHz to 4.0 GHz: < 1.15	> 50 kHz			0.130 dB	0.110 dB
	> 4.0 GHz to 8.0 GHz: < 1.22					
	> 8.0 GHz to 18 GHz: < 1.30		67 pW	42 pW		
NRP-Z98	9 kHz to 2.4 GHz: < 1.11	_			0.047 dB to	0.022 dB to
	> 2.4 GHz to 4.0 GHz: < 1.15				0.083 dB	0.066 dB
	> 4.0 GHz to 6.0 GHz: < 1.22					
Power sensor		T				
NRP-Z27	DC to 2.0 GHz: < 1.15	_			0.070 dB to	0.032 dB
	> 2.0 GHz to 4.2 GHz: < 1.18				0.112 dB	
	> 4.2 GHz to 8.0 GHz: < 1.23					
	> 8.0 GHz to 12.4 GHz: < 1.25					
	> 12.4 GHz to 18.0 GHz:< 1.35		200 nW	120 nW		
NRP-Z37	DC to 2.0 GHz: < 1.15	-			0.070 dB to	0.032 dB
	> 2.0 GHz to 4.2 GHz: < 1.18				0.122 dB	
	> 4.2 GHz to 8.0 GHz: < 1.23					
	> 8.0 GHz to 12.4 GHz: < 1.25					
	> 12.4 GHz to 18.0 GHz:< 1.30					
	> 18.0 GHz to 26.5 GHz:< 1.45					

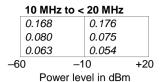
## Two-path power sensors in R&S®Smart Sensor Technology

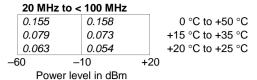
## R&S®NRP-Z211/-Z221 two-path diode universal power sensors

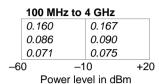
Specifications from 8 GHz to 18 GHz apply only to the R&S®NRP-Z221.

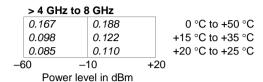
Fraguenay ranga	R&S®NRP-Z211	10 MHz to 8 GHz				
Frequency range		10 MHz to 18 GHz				
Immediate a matchine (CMD)	R&S®NRP-Z221					
Impedance matching (SWR)	10 MHz to 2.4 GHz	< 1.13 (1.11)	( ) 45 00 + 25 00			
	> 2.4 GHz to 8.0 GHz	< 1.20 (1.18)	( ): +15 °C to +35 °C			
	> 8.0 GHz to 18.0 GHz	< 1.25 ( <b>1.23</b> )	ID : 00 ID )			
Power measurement range	continuous average	1.0 nW to 100 mW (–60 d				
	burst average	1.0 μW to 100 mW (–30				
	timeslot/gate average	3.0 nW to 100 mW (-55				
	trace	50 nW to 100 mW (-43 d				
Max. power	average power	0.4 W (+26 dBm), continu				
	peak envelope power	2.0 W (+33 dBm) for max	c. 10 μs			
Measurement subranges	path 1	-60 dBm to -5 dBm				
	path 2	-33 dBm to +20 dBm				
Transition regions	with automatic path selection <sup>3</sup>	$(-10 \pm 1)$ dBm to $(-4 \pm 1)$	) dBm			
Dynamic response	video bandwidth	> 40 kHz (50 kHz)				
	single-shot bandwidth	> 40 kHz (50 kHz) ( ): +15 °C to +3				
	rise time 10 %/90 %	< 10 µs (8 µs)				
Acquisition	sample rate (continuous)	133.358 kHz (default) or	119.467 kHz <sup>4</sup>			
Triggering	internal					
	threshold level range	-33 dBm to +20 dBm				
	threshold level accuracy	identical to uncertainty for absolute power				
	,	measurements				
	threshold level hysteresis	0 dB to 10 dB				
	dropout <sup>5</sup>	0 s to 10 s				
	external	see R&S®NRX base unit	R&S®NRP-Z3 USB			
		adapter cable or R&S®NRP-Z5 USB sensor h				
	slope (external, internal)	pos./neg.				
	delay	-5 ms to +100 s				
	hold-off	0 s to 10 s				
	resolution (delay, hold-off, dropout)	sample period (≈ 8 µs)				
	source	internal, external, immed	iate, bus, hold			
Zero offset	initial, without zeroing	internal, external, initio	1010, 200, 11010			
	path 1	< 1.88 [2.0] (0.6) nW				
	path 2	< 0.94 [1.0] (0.3) µW				
	after external zeroing 6, 7		( ): typical at 1 GHz			
	path 1	< 370 [390] (290) pW	+15 °C to +35 °C			
	path 2	< 180 [190] (145) nW +15 °C to -				
Zero drift 8	path 1	. 4.40 [4.50] (0)\\\				
	path 2	< 60 [65] (0) nW	[ ]: 8 GHz to 18 GHz			
Measurement noise 9	path 1	< 230 [240] (180) pW				
Measurement noise		< 110 [116] (90) nW				

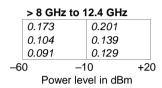
## Uncertainty for absolute power measurements 10 in dB

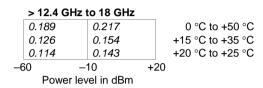




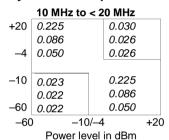


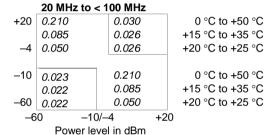


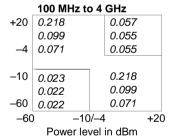


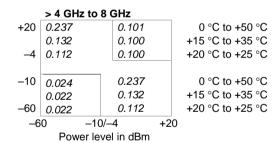


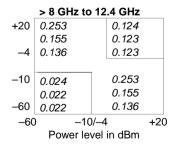
#### Uncertainty for relative power measurements 11 in dB

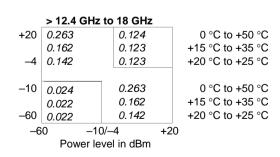












# Additional characteristics of the R&S®NRP-Z211/-Z221 two-path diode power sensors

Sensor type	R&S®NRP-Z211/-Z221	two-path diode power sensor			
Measurand		power of incident wave			
		power of source (DUT) into 50 Ω 12			
RF connector	R&S®NRP-Z211/-Z221	N (male)			
RF attenuation <sup>13</sup>	R&S®NRP-Z211/-Z221	not applicable			
Measurement functions	stationary and recurring waveforms	continuous average			
		burst average			
		timeslot/gate average			
		trace			
	single events	trace			
Continuous average function	measurand	mean power over recurring acquisition interval			
	aperture	10 μs to 300 ms (20 ms default)			
	window function	uniform or von Hann 14			
	duty cycle correction 15	0.001 % to 99.999 %			
	capacity of measurement buffer 16	1 to 1024 results			
Burst average function	measurand	mean power over burst portion of			
_		recurring signal (trigger settings required)			
	detectable burst width				
	R&S®NRP-Z211/-Z221	25 μs to 50 ms			
	minimum gap between bursts	10 μs			
	dropout period <sup>17</sup> for burst end detection 0 to 3 ms				
	exclusion periods <sup>18</sup>				
	start	0 to burst width			
	end	0 s to 3 ms			
	resolution (dropout and exclusion periods)	sample period (≈ 8 µs)			
Timeslot/gate average function	measurand	mean power over individual			
		timeslots/gates of recurring signal			
	number of timeslots/gates	1 to 128 (consecutive)			
	nominal length	10 µs to 0.1 s			
	start of first timeslot/gate	at delayed trigger event			
	exclusion periods 18				
	start	0 to nominal length			
	end	0 s to 3 ms			
	resolution (nominal length and exclusion periods)	sample period (≈ 8 µs)			
Trace function	measurand	mean power over pixel length			
	acquisition				
	length (△)	100 μs to 300 ms			
	start (referenced to delayed trigger)	–5 ms to +100 s			
	result				
	pixels (M)	1 to 1024			
	resolution (△/M)				
	non recurring or internally triggered	≥ 10 µs			
	recurring and externally triggered	≥ 2.5 µs			

Averaging filter	modes	auto off (fixed averaging number)
Averaging inter	modes	auto on (continuously auto-adapted)
		auto once (automatically fixed once)
	auto off	date crise (daternationly fixed crise)
	supported measurement functions	all
	averaging number	$2^N$ ; $N = 0$ to 16 (13 for trace function)
	auto on/once	_ ,
	supported measurement functions	continuous average, burst average,
		timeslot/gate average
	normal operating mode	averaging number adapted to resolution setting and power to be measured
	fixed noise operating mode	averaging number adapted to specified noise content
	result output	
	moving mode	continuous, independent of averaging
	roto	number can be limited to 0.1 s <sup>-1</sup>
	rate	only final result
Attenuation correction	repeat mode function	corrects the measurement result by
Attenuation correction	Tunction	means of a fixed factor (dB offset)
	range	-200.000 dB to +200.000 dB
Embedding	function	incorporates a two-port device at the
Embedding	Turicuori	sensor input so that the measurement
		plane is shifted to the input of this device
	parameters	$S_{11}$ , $S_{21}$ , $S_{12}$ and $S_{22}$ of device
	frequencies	1 to 1000
Gamma correction	function	removes the influence of impedance
		mismatch from the measurement result so that the power of the source (DUT) into 50 $\Omega$ can be read
	parameters	magnitude and phase of reflection
Frequency response correction	function	coefficient of source (DUT) takes the frequency response of the
Frequency response correction	Turicuon	sensor section and of the RF power
		attenuator into account (if applicable)
	parameter	center frequency of test signal see specification of calibration uncertainty
	residual uncertainty	
		and uncertainty for absolute and relative power measurements
Measurement times 19	continuous average	$2 \times (aperture + 145 \ \mu s) \times 2^{N} + t_{z}$
measurement times	buffered <sup>16</sup> , without averaging	$2 \times (aperture + 145 \mu s) \times 2 + t_z$ $2 \times (aperture + 166 \mu s) \times buffer size + t_z$
2 <sup>N</sup> : averaging number	timeslot/gate average	2 x (aperture + 100 µs) x buller size + tz
T: set number of timeslots	signal period – $T \times w > 100 \mu s$	$\leq 2 \times \text{signal period} \times (2^N + \frac{1}{2}) + t_z$
w: nominal length of timeslot	all other cases	$\leq 4 \times \text{signal period} \times (2^N + \frac{1}{4}) + t_z$
w. Horning Torigin of timestot	all other cases	$t_z$ : < 1.6 ms
Measurement speed	continuous average	
without averaging	single-triggered	550 s <sup>-1</sup> (typ.)
aperture time = 10 μs	buffered 16	3000 s <sup>-1</sup> (typ.)
Zeroing (duration)	depends on setting of averaging filter	
	auto on	4 s
	auto off, integration time 20	
	< 4 s	4 s
	4 s to 16 s	integration time
	> 16 s	16 s

## Version 11.00, November 2018

Measurement error due to	R&S®NRP-Z211/-Z221: all paths	n = 2	n = 3	n: multiple		
harmonics <sup>21</sup>	–30 dBc	< 0.001 dB	< 0.003 dB	of carrier		
	–20 dBc	< 0.002 dB	< 0.010 dB	frequency		
	–10 dBc	< 0.010 dB	< 0.040 dB			
Measurement error due to modulation <sup>22</sup>	general	depends on CC signal	DF and RF band	dwidth of test		
	WCDMA (3GPP test model 1-64)					
	worst case	-0.02 dB to +0.	07 dB			
	typical	-0.01 dB to +0.	03 dB			
Change of input reflection co-	R&S®NRP-Z211/-Z221					
efficient with respect to power 23	10 MHz to 2.4 GHz	< 0.02 (0.01)	(): +15 °C to	+35 °C		
	> 2.4 GHz	< 0.03 (0.02)	1			
Calibration uncertainty <sup>24</sup>	R&S®NRP-Z211/-Z221	path 1	path 2			
	10 MHz to < 100 MHz	0.052 dB	0.053 dB			
	100 MHz to 4.0 GHz	0.061 dB	0.062 dB			
	> 4.0 GHz to 8.0 GHz	0.075 dB	0.076 dB			
	> 8.0 GHz to 12.4 GHz	0.080 dB	0.080 dB			
	> 12.4 GHz to 18.0 GHz	0.101 dB	0.102 dB			
Interface to host	power supply	+5 V/0.2 A (US	B high-power de	vice)		
	remote control		as a USB device (function) in full-speed mode, compatible with USB 1.0/1.1/2.0 specifications			
	trigger input	differential (0 V	/+3.3 V)			
	connector type	ODU Mini-Snap	® L series,			
		six-pole cylindri	cal straight plug			
	permissible total cable length	≤ 10 m (see als	≤ 10 m (see also tables on page 28)			
Dimensions (W × H × L)	R&S®NRP-Z211/-Z221	48 mm × 31 mr	48 mm × 31 mm × 170 mm			
•		(1.89 in × 1.22	$(1.89 \text{ in} \times 1.22 \text{ in} \times 6.69 \text{ in})$			
	length including connecting cable	approx. 1.6 m (	approx. 1.6 m (62.99 in)			
Weight	R&S®NRP-Z211/-Z221	< 0.30 kg (0.66	lb)			

## Wideband power sensors in R&S®Smart Sensor Technology

## R&S®NRP-Z81/-Z85/-Z86 wideband power sensors

Specifications from DC to 18 GHz apply to the R&S®NRP-Z81. Specifications from DC to 40 GHz apply to the R&S®NRP-Z85 and R&S®NRP-Z86 model .40. Specifications from DC to 44 GHz apply to the R&S®NRP-Z86 model .44.

Francisco de la constancia de la constan	R&S®NRP-Z81	50 MHz to 10 CHz		
Frequency range	R&S®NRP-Z85	50 MHz to 18 GHz		
	R&S®NRP-Z85 R&S®NRP-Z86 model .40	50 MHz to 40 GHz		
		50 MHz to 40 GHz		
	R&S®NRP-Z86 model .44	50 MHz to 44 GHz		
Impedance matching (SWR)	50 MHz to 2.4 GHz	< 1.16 (1.11)		
	> 2.4 GHz to 8.0 GHz	< 1.20 (1.18)	()45 00 to .25 00	
	> 8.0 GHz to 18.0 GHz	< 1.25 (1.23)	( ): +15 °C to +35 °C	
	> 18.0 GHz to 26.5 GHz	< 1.30 (1.28)	_	
	> 26.5 GHz to 40.0 GHz	< 1.35 (1.33)		
	> 40.0 GHz to 44.0 GHz	< 1.40 (1.38)		
Power measurement range	continuous average	1 nW to 100 mW (-60 dE	3m to +20 dBm)	
	burst			
	full video bandwidth	20 μW to 100 mW (–17 c		
	300 kHz	4 μW to 100 mW (–24 dE		
	trace, timeslot/gate	20 nW to 100 mW (-47 d		
	statistics	4 μW <sup>25</sup> to 100 mW (–24		
Max. power	average power	0.2 W (+23 dBm), continu		
	peak envelope power	1.0 W (+30 dBm) for max	κ. 1 μs	
Dynamic response	video bandwidth	≥ 30 MHz <sup>26</sup>		
	single-shot bandwidth	≥ 30 MHz <sup>26</sup>		
	video bandwidth setting	full (≥ 30 MHz), 5 MHz, 1.5 MHz, 300 kHz		
	rise time 10 %/90 %			
	full video bandwidth	≤ <b>13 ns</b> <sup>26</sup> (f ≥ 500 MHz)		
		< 40 ns <sup>26</sup> (f < 500 MHz)		
	5 MHz	< 75 ns		
	1.5 MHz	< 250 ns		
	300 kHz	< 1.2 µs		
	detectable burst width	≥ 50 ns <sup>26</sup> (f ≥ 500 MHz, full video bandwidth)		
	overshoot	≤ 5 %		
Acquisition	sample rate [period]			
•	full video bandwidth	$80 \times 10^6 \mathrm{s}^{-1} [12.5 \mathrm{ns}]$		
	5 MHz	$40 \times 10^6 \mathrm{s}^{-1} [25.0 \mathrm{ns}]$		
	1.5 MHz	$10 \times 10^6 \mathrm{s}^{-1} [100 \mathrm{ns}]$		
	300 kHz	$2.5 \times 10^6 \mathrm{s}^{-1} [400 \mathrm{ns}]$		
	capture length	50 ns to 1 s (depending of	on meas, function)	
	time base accuracy	±50 ppm		
	time base jitter	< 1 ns		
Triggering	internal	1110		
	threshold level range	-30 dBm to +20 dBm (us	able from	
	threshold level range	-30 dBm to +20 dBm (usable from -22 dBm with full video bandwidth)		
	threshold level accuracy	identical to uncertainty fo		
	threshold level accuracy	measurements	absolute power	
	threshold level hysteresis	0 dB to 10 dB		
	dropout <sup>5</sup>	0 s to 10 s		
			D&C®NIDD 70 LICD	
	external	see R&S®NRX base unit adapter cable or R&S®NI		
		<u> </u>	XF-ZO UOD SENSOF NUD	
	slope (external, internal)	pos./neg.		
	delay	–51.2 μs to +10 s		
	hold-off	0 s to 10 s		
	resolution (delay, hold-off, dropout)	sample period		
	source	internal, external, immediate, bus, hold		

Zero offset		R&S®NRP-Z81	R&S®NRP-Z85/-Z86			
After external zeroing <sup>27</sup>	continuous average					
(): typical at 1 GHz	10 µs aperture time	< 400 (220) pW	< 460 (235) pW			
	other durations	< 10.0 (2.0) nW	< 11.4 (2.2) nW			
	burst/timeslot/gate average, trace	(pixel mean)				
	with averaging	< 10.0 (2.0) nW	< 11.4 (2.2) nW			
	without averaging	< 200 (100) nW	< 230 (110) nW			
	statistics	< 200 (100) nW	< 230 (110) nW			
Zero drift 8, 27		R&S®NRP-Z81	R&S®NRP-Z85/-Z86			
	continuous average	continuous average				
	10 µs aperture time	< 200 pW	< 230 pW			
	other durations	< 500 pW	< 570 pW			
	burst/timeslot/gate average, trace	(pixel mean)	•			
	with averaging	< 2.0 nW	< 2.3 nW			
	without averaging	< 150 nW	< 170 nW			
	statistics	< 150 nW	< 170 nW			
Measurement noise 27, 28		R&S®NRP-Z81	R&S®NRP-Z85/-Z86			
( ): typical at 1 GHz	continuous average <sup>29</sup>					
	10 µs aperture time	< 200 (110) pW	< 230 (120) pW			
	other durations	< 5.0 (1.0) nW	< 5.7 (1.1) nW			
	trace/statistics (noise per sample)					
	full video bandwidth	< <b>3.0</b> (2.0) μW	< <b>3.5</b> (2.2) μW			
	5 MHz	< 1.5 (1.0) µW	< 1.7 (1.1) μW			
	1.5 MHz	< 0.9 (0.6) µW	< 1.0 (0.7) µW			
	300 kHz	< 0.6 (0.4) µW	< 0.7 (0.5) µW			
	burst/timeslot/gate average	Multiply the noise-per	-sample specification for			
	trace (pixel mean)	full video bandwidth v	vith noise reduction factors			
		from tables B and C.	For gate (pixel) lengths			
		≥ 2 µs, a noise value	of 5 nW or better can be			
		achieved with adequa	ite averaging.			
Uncertainty for absolute power		R&S®NRP-Z81	R&S®NRP-Z85/-Z86			
measurements 30	50 MHz to < 100 MHz	0.15 dB (3.5 %)	0.15 dB (3.5 %)			
0 °C to +50 °C	100 MHz to 8.0 GHz	0.13 dB (3.0 %)	0.13 dB (3.0 %)			
	> 8.0 GHz to 18.0 GHz	0.15 dB (3.5 %)	0.15 dB (3.5 %)			
	> 18.0 GHz to 26.5 GHz	_	0.15 dB (3.5 %)			
	> 26.5 GHz to 40.0 GHz	_	0.17 dB (4.0 %)			
	> 40.0 GHz to 44.0 GHz	_	0.19 dB (4.5 %)			

## Uncertainty for relative power measurements <sup>31</sup> in dB

	1 GHz	to 18	GHz			
+20	0.179		0.116		0.064	
	0.155		0.105		0.058	
	0.148		0.102		0.056	
+10	0.145		0.094		0.116	
	0.114		0.079		0.105	
-15	0.105		0.075		0.102	
-10	0.064		0.145		0.179	
	0.045		0.114		0.155	
-60	0.039		0.105		0.148	
	-60	-1	5	+′	10	+20

Power level in dBm

	50 MHz to > 18 GHz to							
+20	0.193	0.130	0.088		0 °C to +50 °C			
	0.170	0.120	0.083		+15 °C to +35 °C			
	0.165	0.117	0.083		+20 °C to +25 °C			
+10	0.162	0.110	0.130		0 °C to +50 °C			
	0.134	0.098	0.120		+15 °C to +35 °C			
-15	0.126	0.095	0.117		+20 °C to +25 °C			
	0.068	0.162	0.193		0 °C to +50 °C			
	0.051	0.134	0.170		+15 °C to +35 °C			
-60	0.046	0.126	0.165		+20 °C to +25 °C			
	-60 -	-15	+10	+20				
	Power level in dBm							

### Table A Multipliers for zero offset, zero drift and noise specifications

Use these multipliers to calculate zero offset, zero drift and noise when operating the sensor at power levels above –20 dBm, at frequencies below 500 MHz, or at temperatures other than +23 °C.

P	ower	≤ –20 dBm	-10 dBm	–5 dBm	0 dBm	5 dBm	10 dBm	15 dBm	20 dBm
Temperature									
0 °C		<b>0.8</b> [0.9]	<b>0.9</b> [1.0]	<b>1.4</b> [1.5]	<b>3.2</b> [3.5]	<b>7.5</b> [8.5]	<b>17</b> [18]	<b>35</b> [37]	<b>65</b> [70]
+15 °C		<b>0.9</b> [1.0]	<b>1.1</b> [1.2]	<b>1.6</b> [1.8]	<b>3.4</b> [3.6]	<b>7.5</b> [8.5]			
+23 °C		<b>1.0</b> [1.2]	<b>1.3</b> [1.5]	<b>1.8</b> [2.0]	<b>3.5</b> [3.8]	<b>7.6</b> [8.7]			
+35 °C		<b>1.4</b> [1.7]	<b>1.7</b> [2.1]	<b>2.3</b> [2.6]	<b>3.9</b> [4.3]	<b>7.8</b> [9.0]			
+50 °C		<b>2.5</b> [3.0]	<b>2.7</b> [3.3]	<b>3.3</b> [4.0]	<b>5.2</b> [5.4]	<b>8.7</b> [9.5]			

[ ] At frequencies < 500 MHz.

### Table B Noise reduction factors for gating and smoothing

The noise reduction factors in this table describe how measurement noise is reduced if the mean value of adjacent samples is taken over a time interval. The time interval can be the length of a gate, timeslot, or pixel in trace mode. Without averaging or for single events, use the leftmost column. If averaging is activated, use the columns for the individual repetition rates and additionally apply multipliers from table C. The repetition rate is identical to the frequency of the measurement being carried out, i.e. the inverse of the trigger period.

Repetition rate	0	10 s <sup>-1</sup>	100 s <sup>-1</sup>	10 <sup>3</sup> s <sup>-1</sup>	10 <sup>4</sup> s <sup>-1</sup>	$5 \times 10^4  \text{s}^{-1}$	10 <sup>5</sup> s <sup>-1</sup>
Gate							
(pixel) length							
25 ns				0.7			
50 ns				0.5			
100 ns				0.4			
200 ns				0.3			
500 ns				0.2			
1 µs	0.16		0.15		0.14		
2 µs	0.14	0.13	0.12	0.11		0.10	
10 µs	0.11	0.1	0.09	0.08	0.07	0.06	
100 µs	0.10	0.09	0.07	0.06	0.04		
1 ms	0.10	0.07	0.06	0.035			
10 ms	0.10	0.06	0.035				

#### Table C Noise reduction factors for averaging

Averaging number	2	4	8	16	32	64	128	256	512	1k	2k	4k	8k
Reduction factor	0.7	0.5	0.35	0.25	0.18	0.13	0.09	0.063	0.044	0.031	0.022	0.016	0.011

Example: A power measurement on a radar pulse is carried out by means of the timeslot/gate function. The gate length is set to 1  $\mu$ s, and the averaging number to 32. The pulse repetition rate is 100 Hz, and the measurement is performed at +15 °C ambient temperature. The pulse power is about -10 dBm.

From the specifications, a  $2\sigma$  noise-per-sample value of 2  $\mu$ W (typ.) can be derived for reference conditions. Applying a multiplier of 1.1 from table A for +15 °C ambient temperature and -10 dBm pulse power results in 2.2  $\mu$ W sampling noise under measurement conditions. Gating reduces noise by a factor of 0.15 (table B), and averaging further reduces noise by a factor of 0.18 (table C). The residual  $2\sigma$  noise of mean power within the gate can then be calculated as follows: 2.2  $\mu$ W × 0.15 × 0.18 = 59 nW (0.06 % of measured value).

# Additional characteristics of the R&S®NRP-Z81/-Z85/-Z86 wideband power sensors

Sensor type		wideband diode power sensor	
Measurand		power of incident wave	
		power of source (DUT) into 50 $\Omega$ 12	
RF connector	R&S®NRP-Z81	N (male)	
	R&S®NRP-Z85	2.92 mm (male)	
	R&S®NRP-Z86	2.40 mm (male)	
Measurement functions	stationary and recurring waveforms	continuous average	
	and the state of t	burst	
		timeslot/gate	
		trace, statistics	
	single events	trace, statistics	
Continuous average function	measurand	mean power over recurring acquisition interval	
oonmaada araraga ramaman	aperture	1 µs to 1 s (10 µs default)	
	window function	uniform or von Hann 14	
	duty cycle correction <sup>15</sup>	0.001 % to 99.999 %	
	capacity of measurement buffer <sup>16</sup>	1 to 8192 results	
Burst average function	measurand	mean power over burst portion of recurring signa	
buist average function	measurand	(trigger settings required)	
	detectable burst width	50 ns to 0.1 s	
	minimum gap between bursts	40 ns	
	dropout period <sup>17</sup> for burst end	0 s to 0.1 s	
	detection	0 \$ 10 0.1 \$	
	exclusion periods <sup>18</sup>		
	·	0 to burst width	
	start		
	end	0 s to 51.2 μs	
	resolution (dropout and exclusion periods)	sample period	
Time alet/gate function	· · · · · · · · · · · · · · · · · · ·	mann mayimum and minimum navor avar	
Timeslot/gate function	measurand	mean, maximum and minimum power over	
	accept on of time a data/mates	individual timeslots/gates of recurring signal	
	number of timeslots/gates	1 to 16 (consecutive)	
	nominal length	50 ns to 0.1 s	
	start of first timeslot/gate	at delayed trigger event	
	exclusion periods <sup>18</sup>	O to a service of low with	
	start	0 to nominal length	
	fence	0 s to 0.1 s (anywhere within timeslot)	
	end	0 s to 51.2 μs	
	resolution	12.5 ns	
	(nominal length and exclusion periods)		
Trace function	measurand	mean, random, maximum and minimum power	
		over pixel length	
	acquisition	1	
	length (4)	50 ns to 1 s	
	start (referenced to delayed trigger)	$-4096 \times \Delta/M \text{ to } +10 \text{ s}$	
	result		
	pixels (M)	3 to 8192	
	resolution (\(\Delta/M\)		
	normal	≥ sample period	
	equivalent time	≥ 100 ps	
	automatic pulse measurements	pulse width, pulse period, pulse off time,	
		pulse duty cycle, pulse rise time, pulse fall time,	
		pulse start time, pulse stop time,	
		pulse top power, pulse base power,	
		pulse peak power, pulse average power,	
		positive overshoot, negative overshoot	

01-11-11 6		0005 005		
Statistics functions	measurand	CCDF or PDF over accumulated records		
	acquisition mode	recurring or triggered		
	length (aperture)	10 µs to 0.3 s		
	start (referenced to delayed trigger)	0 s to +10 s		
	exclusion period (fence)	0 s to 0.3 s (anywhere within aperture)		
	number of accumulated records	$2^{N}$ ; $N = 0$ to 16 (set by averaging number)		
	result	2 , W = 0 to 10 (set by averaging number)		
	number of histogram classes (C)	3 to 8192		
	power span (S)	0.01 dB to 100 dB		
	minimum class width (S/C)	0.006 dB		
Averaging filter	modes	auto off (fixed averaging number)		
Averaging inter	modes	auto on (continuously auto-adapted)		
		auto one (automatically fixed once)		
	auto off	auto once (automatically fixed once)		
		all		
	supported measurement functions	$2^N$ ; $N = 0$ to 20 (16 for trace/statistics)		
	averaging number auto on/once	2 , N = 0 to 20 (10 for trace/statistics)		
	supported measurement functions	continuous average hurst average timeslet/get		
	supported measurement functions	continuous average, burst average, timeslot/gate		
	normal aparating made	averaging number edepted to recolution actting		
	normal operating mode	averaging number adapted to resolution setting and power to be measured		
	fixed noise operating mode	averaging number adapted to specified noise content		
	result output			
	moving mode	continuous, independent of averaging number		
	rate	can be limited to 0.1 s <sup>-1</sup>		
	repeat mode	only final result		
Attenuation correction	function	corrects the measurement result by means of a fixed factor (dB offset)		
	range	-200.000 dB to +200.000 dB		
Embedding	function	incorporates a two-port device at the sensor inpu so that the measurement plane is shifted to the input of this device		
	parameters	$S_{11}$ , $S_{21}$ , $S_{12}$ and $S_{22}$ of device		
	number of devices	user-definable		
	frequencies (sum of all devices)	≤ 32000		
Gamma correction	function	removes the influence of impedance mismatch from the measurement result so that the power of		
		·		
	norometero	the source (DUT) into 50 Ω can be read		
	parameters	magnitude and phase of reflection coefficient of source (DUT)		
Frequency response correction	function	takes the frequency response of the power		
		sensor into account		
	parameter	center frequency of test signal		
	residual uncertainty	see specification of calibration uncertainty and		
	,	uncertainty for absolute power measurements		
Measurement time 19	continuous average	, , , , , , , , , , , , , , , , , , , ,		
	single-triggered	$2 \times (aperture + 6.5 \mu s) \times 2^N + t_z$		
2 <sup>N</sup> : averaging number	buffered <sup>16</sup> , without averaging	$2 \times (aperture + 50 \mu s) \times buffer size + t_z$		
T: number of timeslots	,a. aroluging	$t_z$ : < 1.6 ms		
w: nominal length of timeslot	timeslot/gate average	,		
	signal period – $T \times w > 6 \mu s$	$\leq$ signal period $\times$ (2 <sup>N</sup> + 1) + $t_{\rm f}$		
	all other cases	$\leq 2 \times \text{signal period} \times (2^N + \frac{1}{2}) + t_i$		
	an other cases	$t_i$ : 3 ms (typ.)		
Measurement speed	continuous average			
without averaging	single-triggered	960 s <sup>-1</sup> (typ.)		
aperture time = 1 µs	buffered <sup>16</sup>	9800 s <sup>-1</sup> (typ.)		
aportare time = 1 µs	Dulleled	2000 3 (typ.)		

## Version 11.00, November 2018

Zeroing (duration)	including all functions, entire	8 s			
	frequency range				
	restricted to < 500 MHz, all functions	4 s			
	restricted to ≥ 500 MHz, all functions				
	restricted to trace and statistics	20 ms			
	function, entire frequency range				
Measurement error due to	n = 3	≤ 4 GHz 4 GHz to 12.4	4 GHz > 12.4 GHz		
harmonics 32	–60 dBc	< 0.004 dB < 0.003 dB	3 < 0.003 dB		
	–40 dBc	< 0.035 dB < 0.030 dB	3 < 0.025 dB		
n: multiple of carrier frequency	–20 dBc	< 0.350 dB < 0.300 dB	3 < 0.250 dB		
	n = 2	≤ 4 GHz 4 GHz to 8 G	Hz > 8 GHz		
	-60 dBc	< 0.001 dB < 0.002 dB	3 < 0.003 dB		
	–40 dBc	< 0.010 dB < 0.017 dB	3 < 0.025 dB		
	–20 dBc	< 0.100 dB < 0.170 dB	3 < 0.250 dB		
Change of input reflection	-10 dBm to -60 dBm	< 0.035 (0.010)			
coefficient with respect to	-10 dBm to 0 dBm	< 0.035 (0.025)	( ): <i>f</i> ≤ 4 GHz		
power <sup>33</sup>	-10 dBm to +10 dBm	< 0.075 (0.055)	+15 °C to +35 °C		
	-10 dBm to +20 dBm	< 0.090 (0.080)			
Calibration uncertainty 34		R&S®NRP-Z81	R&S®NRP-Z85/-Z86		
•	50 MHz to < 100 MHz		0.069 dB (1.6 %)		
	≥ 100 MHz to 2.4 GHz	0.052 dB (1.2 %)	0.052 dB (1.2 %)		
	> 2.4 GHz to 4.0 GHz	, ,	0.056 dB (1.3 %)		
	> 4.0 GHz to 8.0 GHz	0.056 dB (1.3 %)	0.060 dB (1.4 %)		
	> 8.0 GHz to 12.5 GHz	0.073 dB (1.7 %)	0.073 dB (1.7 %)		
	> 12.5 GHz to 18.0 GHz	0.086 dB (2.0 %)	0.090 dB (2.1 %)		
	> 18.0 GHz to 26.5 GHz	. ,	0.086 dB (2.0 %)		
	> 26.5 GHz to 40.0 GHz	_	0.116 dB (2.7 %)		
	> 40.0 GHz to 44.0 GHz	_	0.149 dB (3.5 %)		
Interface to host	power supply	+5 V/0.5 A (USB high-pow	er device)		
	remote control	as a USB device (function)			
		compatible with USB 1.0/1.1/2.0 specifications			
	trigger input	differential (0 V/+3.3 V)			
	connector type	ODU Mini-Snap® L series,			
		six-pole cylindrical straight plug			
	permissible total cable length	≤ 5 m (see also tables on page 28)			
Dimensions	W×H×L		48 mm × 31 mm × 170 mm		
		(1.89 in × 1.22 in × 6.69 in)	)		
	length including connecting cable	approx. 1.6 m (62.99 in)			
Weight		< 0.30 kg (0.66 lb)			

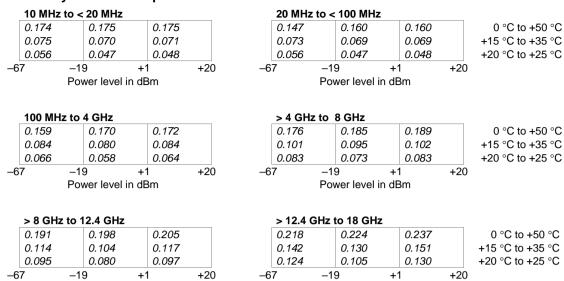
# Level control sensors in R&S®Smart Sensor Technology

## R&S®NRP-Z28 level control sensor

Frequency range		10 MHz to 1	8 GHz		
Impedance matching (SWR) and		input	output	insertion loss 36	
insertion loss		SWR	SWR 35	(): typical	
	10 MHz to 2.4 GHz	< 1.35	< 1.11	< <b>8.0</b> (7.0) dB	
	> 2.4 GHz to 4.0 GHz	< 1.45	< 1.15	< <b>8.5</b> (7.5) dB	
	> 4.0 GHz to 8.0 GHz	< 1.75	< 1.22	< <b>9.5</b> (8.5) dB	
	> 8.0 GHz to 12.4 GHz	< 1.80	< 1.30	< <b>10.5</b> (9) dB	
	> 12.4 GHz to 18.0 GHz	< 1.90	< 1.30	< <b>11.0</b> (10) dB	
Power measurement range	continuous average	200 pW to 1	00 mW (–67 d	dBm to +20 dBm)	
RF output	burst average			dBm to +20 dBm)	
•	timeslot/gate average			dBm to +20 dBm) 1	
	trace	<u> </u>		Bm to +20 dBm) 2	
Max. power	average power			,	
RF input	10 MHz to 2.4 GHz	0.7 W (+28.	5 dBm)		
F	> 2.4 GHz to 8.0 GHz	0.9 W (+29.		continuous	
	> 8.0 GHz to 12.4 GHz	1.1 W (+30.			
	> 12.4 GHz to 18.0 GHz	1.3 W (+31.			
	peak envelope power			ge power (for 10 µs)	
Measurement subranges	path 1	-67 dBm to		go ροιτοί (ιοι το μο)	
modear official cash angee	path 2	-46 dBm to			
	path 3	-26 dBm to			
Transition regions	with automatic path selection <sup>3</sup>		IBm to (-13 -1	/+2) dBm	
Transition regions	with automatic path selection		3m to (+7 –1/+2		
Dynamic response	video bandwidth	> 50 kHz (1		) dBiii	
Dynamic response	single-shot bandwidth	> 50 kHz (1		( ): +15 °C to +35 °C	
	rise time 10 %/90 %	< 8 μs (4 μs)		( ). 1 10 0 10 100 0	
Acquisition	sample rate (continuous)	133.358 kHz (default) or 119.467 kHz <sup>4</sup>		119 467 kHz <sup>4</sup>	
Triggering	internal	100.000 Ki II	e (doiddir) or	110.107 1012	
11199011119	threshold level range —40 dBm to +20 dBm				
	threshold level accuracy			absolute power	
	measurements		absolute power		
	threshold level hysteresis 0 dB to 10 dB				
	dropout <sup>5</sup>	0 s to 10 s			
	external		RX hase unit	R&S®NRP-Z3 USB	
	CATOTICI		,	RP-Z5 USB sensor hub	
	slope (external, internal)	pos./neg.	io or read ren	20 000 001001 1100	
	delay	_5 ms to +1	00 s		
	hold-off	0 s to 10 s	00 0		
	resolution (delay, hold-off, dropout)	sample period			
	source	internal, external, immediate, bus, hold			
Zero offset	initial, without zeroing	omai, oxt	a.,oui		
	path 1	< 505 [600]	(100) pW	-	
	path 2	< 52 [60] (10			
	path 3	< 5.2 [6] (1)	,,,,		
	after external zeroing 6,7	< 0.2 [0] (1)	μvv	(): typical at 1 GHz	
	path 1	< 114 [132]	(67) n\//	+15 °C to +35 °C	
	path 2				
	path 3	< 11 [13] (6) nW < 1.1 [1.3] (0.6) μW		[ ]: 8 GHz to 18 GHz	
Zero drift <sup>8</sup>	path 1	< 39 [44] (0)			
Zero ariit	path 2	< 3.3 [3.8] (0		-	
	-	< 0.33 [0.38		-	
Measurement noise 9	path 3				
wicasurement noise	path 1	< 72 [83] (4)		-	
	path 2	< 7 [8] (4) n		_	
	path 3	< 0.7 [0.8] (	υ.4) μνν		

Power level in dBm

## Uncertainty for absolute power measurements 10 in dB



Power level in dBm

## Uncertainty for relative power measurements <sup>11</sup> in dB

	10 MHz to < 20 MHz								
+20	0.226	0.229	0.027						
	0.084	0.080	0.022						
+7	0.046	0.044	0.022						
+1	0.226	0.027	0.229						
	0.083	0.022	0.080						
-13	0.045	0.022	0.044						
-19	0.023	0.226	0.226						
	0.022	0.083	0.084						
-67	0.022	0.045	0.046						
-6	7 –19/-	–13 ±0/	+8 +20						
Power level in dBm									

	20 MHz to	< 100 MHz				
+20	0.206	0.215	0.027	0 °C to +50 °C		
	0.082	0.078	0.022	+15 °C to +35 °C		
+7	0.046	0.044	0.022	+20 °C to +25 °C		
			_			
+1	0.205	0.027	0.215	0 °C to +50 °C		
	0.081	0.022	0.078	+15 °C to +35 °C		
-13	0.044	0.022	0.044	+20 °C to +25 °C		
-19	0.023	0.205	0.206	0 °C to +50 °C		
	0.022	0.081	0.082	+15 °C to +35 °C		
-67	0.022	0.044	0.046	+20 °C to +25 °C		
_	67 –19	/-13 ±0	/+8	+20		
Power level in dBm						

	100 MHz to	4 GHz				
+20	0.209	0.218	0.038			
	0.088	0.085	0.032			
+7	0.055	0.047	0.031			
			_			
+1	0.206	0.028	0.218			
	0.083	0.022	0.085			
-13	0.048	0.022	0.047			
-19	0.023	0.206	0.209			
	0.022	0.083	0.088			
-67	0.022	0.048	0.055			
-6	7 –19/-	–13 +1/	+7 +20			
Power level in dRm						

	> 4 GHz to	8 GHz					
+20	0.215	0.223	0.049	0 °C to +50 °C			
	0.097	0.093	0.044	+15 °C to +35 °C			
+7	0.066	0.059	0.043	+20 °C to +25 °C			
+1	0.210	0.030	0.223	0 °C to +50 °C			
	0.088	0.022	0.093	+15 °C to +35 °C			
-13	0.054	0.022	0.059	+20 °C to +25 °C			
-19	0.024	0.210	0.215	0 °C to +50 °C			
	0.022	0.088	0.097	+15 °C to +35 °C			
-67	0.022	0.054	0.066	+20 °C to +25 °C			
_	67 –19	/ <del>-</del> 13 +	1/+7 +	20			
	Power level in dRm						

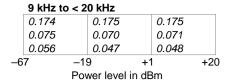
> 8 GHz to 12.4 GHz								
+20	0.224	0.231	0.064					
	0.111	0.106	0.061					
+7	0.084	0.077	0.060					
+1	0.216	0.034	0.231					
	0.096	0.027	0.106					
-13	0.063	0.025	0.077					
-19	0.024	0.216	0.224					
	0.022	0.096	0.111					
-67	0.022	0.063	0.084					
-6	7 –19/-	-13 +1/	+7 +20					
Power level in dBm								

	> 12.4 GHz	to 18 GHz				
+20	0.244	0.245	0.086	0 °C to +50 °C		
	0.135	0.128	0.084	+15 °C to +35 °C		
+7	0.110	0.102	0.083	+20 °C to +25 °C		
+1	0.230	0.040	0.245	0 °C to +50 °C		
	0.112	0.034	0.128	+15 °C to +35 °C		
-13	0.079	0.033	0.102	+20 °C to +25 °C		
-19	0.024	0.230	0.244	0 °C to +50 °C		
	0.022	0.112	0.135	+15 °C to +35 °C		
-67	0.022	0.079	0.110	+20 °C to +25 °C		
_	67 –19/	/ <del>_</del> 13 +1	/+7 +	<del>-</del> 20		
Power level in dBm						

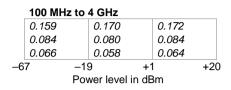
## R&S®NRP-Z98 level control sensor

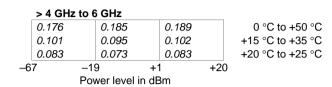
Frequency range		9 kHz to 6	GHz		
Impedance matching (SWR) and insertion loss		input SWR	output SWR <sup>35</sup>	insertion loss <sup>36</sup> ( ): typical	
	9 kHz to 2.4 GHz	< 1.35	< 1.11	< <b>8.0</b> (7.0) dB	
	> 2.4 GHz to 4.0 GHz	< 1.45	< 1.15	< <b>8.5</b> (7.5) dB	
	> 4.0 GHz to 6.0 GHz	< 1.75	< 1.22	< <b>9.5</b> (8.5) dB	
Power measurement range	continuous average	200 pW to	100 mW (-67	dBm to +20 dBm)	
RF output					
Max. power	average power				
RF input	9 kHz to 2.4 GHz	0.7 W (+2	8.5 dBm)	continuous	
	> 2.4 GHz to 6.0 GHz	0.9 W (+2	9.5 dBm)		
	peak envelope power	7.5 dB abo	ove max. avera	ge power (for 10 µs)	
Measurement subranges	path 1	-67 dBm t	o –14 dBm		
	path 2	-46 dBm t	o +6 dBm		
	path 3	-26 dBm t	o +20 dBm		
Transition regions	with automatic path selection <sup>3</sup>	,	dBm to (-13 - dBm to (+7 -1/+	,	
Dynamic response	rise time 10 %/90 %	< 5 ms	,	,	
Acquisition	sample rate (continuous)	133.358 k	Hz		
Zero offset	initial, without zeroing				
	path 1	< 505 (100	0) pW		
	path 2	< 52 (10) 1	ńW		
	path 3	< 5.2 (1) µ	W		
	after external zeroing <sup>6,7</sup>				
	path 1	< 114 (67)	pW		
	path 2	< 11 (6) n\	N	(): typical at 1 GHz	
	path 3	< 1.1 (0.6)	μW	+15 °C to +35 °C	
Zero drift <sup>8</sup>	path 1	< 39 (0) p\	N		
	path 2	< 3.3 (0) n	W		
	path 3	< 0.33 (0)	μW		
Measurement noise 9	path 1	< 72 (42)	Wc		
	path 2	< 7 (4) nW	1		
	path 3	< 0.7 (0.4)	μW		

## Uncertainty for absolute power measurements 10 in dB



	20 kHz	to <	100 MHz	:			
	0.147		0.160		0.160		0 °C to +50 °C
	0.073		0.069		0.069		+15 °C to +35 °C
	0.056		0.047		0.048		+20 °C to +25 °C
-67	7	-19	9	+	1	+20	
		Pον	wer level	in dE	3m		





## Uncertainty for relative power measurements 11 in dB

	9 kHz t	o < 20	kHz			
+20	0.226		0.229		0.027	
	0.084		0.080		0.022	
+7	0.046		0.044		0.022	
+1	0.226		0.027		0.229	
	0.083		0.022		0.080	
-13	0.045		0.022		0.044	
-19	0.023		0.226		0.226	
	0.022		0.083		0.084	
-67	0.022		0.045		0.046	
-6	7	-19/-	13	+1/+7	7	+20
		Powe	er level ir	n dBm		

		_			
	20 kHz to	< 100 MHz			
+20	0.206	0.215	0.027		0 °C to +50 °C
	0.082	0.078	0.022		+15 °C to +35 °C
+7	0.046	0.044	0.022		+20 °C to +25 °C
+1	0.205	0.027	0.215		0 °C to +50 °C
	0.081	0.022	0.078		+15 °C to +35 °C
-13	0.044	0.022	0.044		+20 °C to +25 °C
-19	0.023	0.205	0.206		0 °C to +50 °C
	0.022	0.081	0.082		+15 °C to +35 °C
-67	0.022	0.044	0.046		+20 °C to +25 °C
-6	7 -	-19/–13 +1	/+7	+20	
		Power level in o	dBm		

	100 MHz	to 4 GHz				
+20	0.209	0.218		0.038		
	0.088	0.085		0.032		
+7	0.055	0.047		0.031		
+1	0.206	0.028		0.218		
	0.083	0.022		0.085		
-13	0.048	0.022		0.047		
		_				
-19	0.023	0.206		0.209		
	0.022	0.083		0.088		
-67	0.022	0.048		0.055		
-6	67 -	-19/–13	+1/+7	+20		
	Power level in dBm					

	> 4 GHz to	6 GHz		
+20	0.215	0.223	0.049	0 °C to +50 °C
	0.097	0.093	0.044	+15 °C to +35 °C
+7	0.066	0.059	0.043	+20 °C to +25 °C
+1	0.210	0.030	0.223	0 °C to +50 °C
	0.088	0.022	0.093	+15 °C to +35 °C
-13	0.054	0.022	0.059	+20 °C to +25 °C
-19	0.024	0.210	0.215	0 °C to +50 °C
	0.022	0.088	0.097	+15 °C to +35 °C
-67	0.022	0.054	0.066	+20 °C to +25 °C
-6	7 –1	9/–13 +1	/+7 +20	)
	Po	ower level in c	IBm	

## Additional characteristics of the R&S®NRP-Z28/-Z98 level control sensors

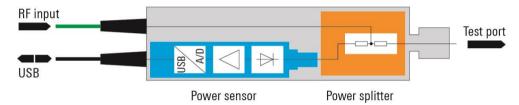
Shaded areas apply only to the R&S®NRP-Z28.

Sensor type		three-path diode power sensor combined with a		
71		resistive power splitter in a power leveling setup		
		(see diagram at the end of this section)		
Measurand		power available on a 50 Ω load		
		power of wave emanating at RF output <sup>12</sup>		
RF connectors		N (male)		
Measurement functions	stationary and recurring waveforms	continuous average		
	, ,	burst average		
		timeslot/gate average		
		trace		
	single events	trace		
Continuous average function	measurand	mean power over recurring acquisition interval		
<b>G</b>	aperture			
	R&S®NRP-Z28	10 μs to 300 ms (20 ms default)		
	R&S®NRP-Z98	1 ms to 300 ms (20 ms default)		
	window function	uniform or von Hann 14		
	duty cycle correction 15	0.001 % to 99.999 %		
	capacity of measurement buffer 16	1 to 1024 results		
Burst average function	measurand	mean power over burst portion of recurring		
		signal (trigger settings required)		
	detectable burst width	20 μs to 50 ms		
	minimum gap between bursts	10 µs		
	dropout period <sup>17</sup> for burst end	0 s to 3 ms		
	detection			
	exclusion periods <sup>18</sup>			
	start	0 to burst width		
	end	0 s to 3 ms		
	resolution (dropout and exclusion	sample period (≈ 8 µs)		
	periods)			
Timeslot/gate average function	measurand	mean power over individual timeslots/gates of		
		recurring signal		
	number of timeslots/gates	1 to 128 (consecutive)		
	nominal length	10 μs to 0.1 s		
	start of first timeslot/gate	at delayed trigger event		
	exclusion periods 18			
	start	0 to nominal length		
	end	0 s to 3 ms		
	resolution (nominal length and	sample period (≈ 8 µs)		
	exclusion periods)			
Trace function	measurand	mean power over pixel length		
	acquisition			
	length (△)	100 μs to 300 ms		
	start (referenced to delayed trigger)	−5 ms to +100 s		
	result			
	pixels (M)	1 to 1024		
	resolution (Δ/M)			
	non recurring or internally	≥ 10 µs		
	triggered			
	recurring and externally	≥ 2.5 µs		
	triggered			

## Shaded areas apply only to the R&S®NRP-Z28.

Averaging filter	modes	auto off(fixed averaging number)
Avoidying inter	modes	auto on(continuously auto-adapted)
		auto once(automatically fixed once)
	auto off	
	supported measurement functions	all
	averaging number	$2^N$ ; $N = 0$ to 16 (13 for trace function)
	auto on/once	
	supported measurement functions	continuous average, burst average, timeslot/gate average
	normal operating mode	averaging number adapted to resolution setting and power to be measured
	fixed noise operating mode	averaging number adapted to specified noise content
	result output	
	moving mode	continuous, independent of averaging number
	rate	can be limited to 0.1 s <sup>-1</sup>
	repeat mode	only final result
Attenuation correction	function	corrects the measurement result by means of a
		fixed factor (dB offset)
	range	-200.000 dB to +200.000 dB
Embedding	function	incorporates a two-port device at the
		RF output so that the measurement plane is
		shifted to the output of this device
	parameters	S <sub>11</sub> , S <sub>21</sub> , S <sub>12</sub> and S <sub>22</sub> of device
Commo correction	frequencies	1 to 1000
Gamma correction	function	removes the influence of impedance mismatch
		from the measurement result so that the power of the wave emanating at the RF output can be
		read
	parameters	magnitude and phase of reflection coefficient of
	parameters	DUT
Frequency response correction	function	takes the frequency response of the sensor
		section and of the power splitter into account
	parameter	center frequency of test signal
	residual uncertainty	see specification of calibration uncertainty and
		uncertainty for absolute and relative power
11 10		measurements
Measurement time 19	continuous average	0 (an artisma 4.45 )
2N. augraging number	R&S®NRP-Z28	$2 \times (aperture + 145  \mu s) \times 2^{N} + t_{z}$
2 <sup>N</sup> : averaging number <i>T</i> : set number of timeslots	R&S®NRP-Z98	$t_z$ : < 1.6 ms 2 × (aperture + 5 ms) × 2 <sup>N</sup> – 3.4 ms + $t_d$
w: nominal length of timeslot	KAO-INKY-ZYO	$2 \times (aperture + 5 \text{ ms}) \times 2^{n} - 3.4 \text{ ms} + t_d$ $t_d$ must be taken into account with activated auto
w. norminariengur or unlesiot		delay (1 ms to 20 ms depending on
		temperature) <sup>37</sup>
	buffered <sup>16</sup> , without averaging	$2 \times (aperture + 250 \mu s) \times buffer size + t_z$
	timeslot/gate average	2 A (aportaro 1 200 po) A bullor 3/20 1 tz
	signal period – T × w > 100 µs	$\leq 2 \times \text{signal period} \times (2^N + \frac{1}{2}) + t_z$
	all other cases	$\leq 4 \times \text{signal period} \times (2^N + \frac{1}{4}) + t_z$
Zeroing (duration)	depends on setting of averaging filter	
,	auto on	4 s
	auto off, integration time <sup>20</sup>	
	< 4 s	4 s
	4 s to 16 s	integration time
	> 16 s	16 s
Measurement error due to		n=2 $n=3$
harmonics <sup>21</sup>	-30 dBc	< 0.001 dB < 0.003 dB <i>n</i> : multiple
	-20 dBc	< 0.002 dB < 0.010 dB of carrier frequency
	-10 dBc	< 0.010 dB < 0.040 dB

Measurement error due to modulation <sup>22</sup>	general	depends on 0 signal	CCDF and RF bar	ndwidth of test	
	WCDMA (3GPP test model 1-64)				
	worst case	-0.02 dB to +	-0.02 dB to +0.07 dB		
	typical	-0.01 dB to +	0.03 dB		
Calibration uncertainty 24		path 1	path 2	path 3	
(R&S®NRP-Z98 up to 6 GHz only)	< 100 MHz	0.056 dB	0.047 dB	0.048 dB	
•	100 MHz to 4.0 GHz	0.066 dB	0.057 dB	0.058 dB	
	> 4.0 GHz to 8.0 GHz	0.083 dB	0.072 dB	0.072 dB	
	> 8.0 GHz to 12.4 GHz	0.095 dB	0.077 dB	0.077 dB	
	> 12.4 GHz to 18.0 GHz	0.124 dB	0.100 dB	0.101 dB	
Interface to host	power supply	+5 V/0.2 A (USB high-power device)			
	remote control	as a USB dev	as a USB device (function) in full-speed mode,		
		compatible w	compatible with USB 1.0/1.1/2.0 specifications		
	trigger input	differential (0	differential (0 V/+3.3 V)		
	connector type	ODU Mini-Sn	ap® L series,		
		six-pole cyline	drical straight plu	g	
	permissible total cable length	≤ 10 m (see a	also tables on pag	ge 28)	
Dimensions	$W \times H \times L$	48 mm × 50 r	nm × 250 mm		
		(1.89 in × 1.9	7 in × 9.84 in)		
	length including connecting cable	approx. 1.75	m (68.89 in)		
Weight		< 0.7 kg (1.54	l lb)		



Block diagram of the R&S®NRP-Z28/-Z98 level control sensors

# Power sensor modules in R&S®Smart Sensor Technology

## R&S®NRP-Z27/-Z37 power sensor modules

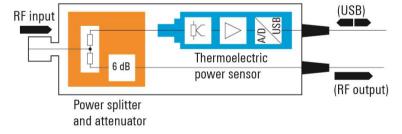
Specifications from 18 GHz to 26.5 GHz apply only to the R&S®NRP-Z37.

Frequency range	R&S®NRP-Z27	DC to 18 GHz			
	R&S®NRP-Z37	DC to 26.5 GHz			
Impedance matching (SWR)	RF input	R&S®NRP-Z27	R&S	®NRP-Z37	
	DC to 2.0 GHz	< 1.15	< 1.1	5	
	> 2.0 GHz to 4.2 GHz	< 1.18	< 1.1	8	
	> 4.2 GHz to 8.0 GHz	< 1.23	< 1.2	23	
	> 8.0 GHz to 12.4 GHz	< 1.25	< 1.2	25	
	> 12.4 GHz to 18.0 GHz	< 1.35	< 1.3	80	
	> 18.0 GHz to 26.5 GHz	-	< 1.4		
	RF output	R&S®NRP-Z27	R&S	®NRP-Z37	
	DC to 8.0 GHz	< 1.6	< 1.6	6	
	> 8.0 GHz to 26.5 GHz	< 2.0	< 2.0	)	
Power measurement range		4 µW to 400 mV	V (-24 dBm to +	-26 dBm),	
		continuous, in a	single range		
Max. power	average power	0.5 W (+27 dBm			
		1.0 W (+30 dBm		inutes	
	peak envelope power	30 W (45 dBm)			
Acquisition	sample rate	20.833 kHz (sig			
Zero offset	after external zeroing 6, 7	< 400 nW (typic	< 400 nW (typically 200 nW at 1 GHz)		
Zero drift <sup>8</sup>			< 160 nW		
Measurement noise 9		< 240 nW (typic			
Uncertainty for absolute power		+20 °C to	+15 °C to	0 °C to	
measurements <sup>38</sup>		+25 °C	+35 °C	+50 °C	
	with matched load on RF output (S)				
	DC to < 100 MHz	0.070 dB	0.077 dB	0.103 dB	
	100 MHz to 4.2 GHz	0.075 dB	0.082 dB	0.106 dB	
	> 4.2 GHz to 8.0 GHz	0.087 dB	0.094 dB	0.119 dB	
	> 8.0 GHz to 12.4 GHz	0.093 dB	0.101 dB	0.130 dB	
	> 12.4 GHz to 18.0 GHz	0.112 dB	0.121 dB	0.151 dB	
	> 18.0 GHz to 26.5 GHz	0.122 dB	0.137 dB	0.190 dB	
	with R&S®FSMR26 connected to R				
	DC to < 100 MHz	0.104 dB	0.109 dB	0.128 dB	
	100 MHz to 4.2 GHz	0.116 dB	0.120 dB	0.138 dB	
	> 4.2 GHz to 8.0 GHz	0.163 dB	0.166 dB	0.181 dB	
	> 8.0 GHz to 18.0 GHz	0.183 dB	0.187 dB	0.207 dB	
	> 18.0 GHz to 26.5 GHz	0.226 dB	0.235 dB	0.269 dB	
	with R&S®FSMR26 connected to R	F output and activated	load interferen	ce correction	
	DC to < 100 MHz	0.067 dB	0.074 dB	0.101 dB	
	100 MHz to 4.2 GHz	0.077 dB	0.083 dB	0.107 dB	
	> 4.2 GHz to 8.0 GHz	0.092 dB	0.099 dB	0.123 dB	
	> 8.0 GHz to 12.4 GHz	0.099 dB	0.107 dB	0.135 dB	
	> 12.4 GHz to 18.0 GHz	0.122 dB	0.130 dB	0.159 dB	
	> 18.0 GHz to 26.5 GHz	0.154 dB	0.167 dB	0.212 dB	
Uncertainty for relative power		0.032 dB			
measurements 39					

## Additional characteristics of the R&S®NRP-Z27/-Z37 power sensor modules

Sensor type			ensor with signal pick-off		
		at RF output (see diagra	am at the end of this		
Measurand		section)	power of incident wave		
weasuranu			power of incident wave power of source (DUT) into 50 $\Omega$ <sup>12</sup>		
RF connectors	input	power or source (DOT)	11110 30 12		
Ni connectors	R&S®NRP-Z27	N (male)			
	R&S®NRP-Z37	3.5 mm (male)			
	RF signal output	3.5 mm (male)			
Insertion loss	DC to 2.0 GHz	< <b>14</b> (12.5) dB			
Between RF input and RF output	> 2.0 GHz to 4.2 GHz	< <b>15</b> (13.5) dB			
between it input and it output	> 4.2 GHz to 4.2 GHz	< <b>16</b> (14.0) dB	(): typical		
	> 8.0 GHz to 12.4 GHz	< <b>17</b> (14.5) dB	( ). typical		
	> 12.4 GHz to 18.0 GHz	< <b>18</b> (15.5) dB			
	> 18.0 GHz to 26.5 GHz	< <b>19</b> (16.5) dB			
Measurement function	stationary and recurring waveforms	continuous average			
Continuous average function	measurand	mean power over recurr	ring acquisition intorval		
Softificuous average function	aperture	1 ms to 100 ms (20 ms			
	window function	uniform or von Hann 14	derauit)		
	duty cycle correction 1515	0.001 % to 99.999 %			
	capacity of measurement buffer <sup>16</sup>	1 to 1024 results			
Averaging filter	modes	auto off (fixed averaging	number)		
Averaging inter	modes	auto on (continuously a			
		auto one (automatically	. ,		
	auto off	auto once (automatically fixed once)			
	averaging number	$2^N$ ; $N = 0$ to 16			
	auto on/once				
	normal operating mode	averaging number adapted to resolution setting			
	normal operating mode	and power to be measured			
	fixed noise operating mode	averaging number adap			
	, ,	content	'		
	result output				
	moving mode	continuous, independen	nt of averaging number		
	rate	can be limited to 0.1 s <sup>-1</sup>			
	repeat mode	only final result			
Attenuation correction	function	corrects the measureme	ent result by means of a		
		fixed factor (dB offset)			
	range	-200.000 dB to +200.00			
Gamma correction	function	removes the influence of	of impedance mismatch		
		from the measurement			
		of the source (DUT) into			
	parameters	magnitude and phase o	f reflection coefficient of		
Frequency response correction	function	source (DUT) takes the frequency res	nonse of the sensor		
requeitey response correction	Turicuon	section and of the power	•		
	parameter	center frequency of test			
	residual uncertainty	see specification of calil			
		uncertainty for absolute			
Load interference correction	function	removing the influence			
		signal output from the p			
		result	SS. Mododromont		
	parameters	magnitude and phase of reflection coefficient of load			
	residual uncertainty	see specification of load interference error			

Measurement time 19		2 x (aperture + 450 μs) x 2		
2 <sup>N</sup> : averaging number		$t_{\rm d}$ (80 ms) must be taken into account when auto		
		delay 37 is active		
Zeroing (duration)	depends on setting of averaging filter			
	auto on	4 s		
	auto off, integration time 20			
	< 4 s	4 s		
	4 s to 16 s	integration time		
	> 16 s	16 s		
Calibration uncertainty 40	DC to < 100 MHz	0.063 dB		
	100 MHz to 4.2 GHz	0.070 dB		
	> 4.2 GHz to 8.0 GHz	0.082 dB		
	> 8.0 GHz to 12.4 GHz	0.088 dB		
	> 12.4 GHz to 18.0 GHz	0.109 dB		
	> 18.0 GHz to 26.5 GHz	0.118 dB		
Temperature effect 41	DC to 4.2 GHz	< 0.004 dB/K		
	> 4.2 GHz to 8.0 GHz	< 0.005 dB/K		
	> 8.0 GHz to 12.4 GHz	< 0.005 dB/K		
	> 12.4 GHz to 18.0 GHz	< 0.006 dB/K		
	> 18.0 GHz to 26.5 GHz	< 0.009 dB/K		
Linearity 42	for power levels < 100 mW (20 dBm)	< 0.020 dB		
Power coefficient 43		< (0.02 + 0.002 f/GHz) dB	W	
Load interference error 44	DC to 2.0 GHz	< 0.061 (0.003) dB	values in ( ) after	
From RF signal output	> 2.0 GHz to 12.4 GHz	< 0.050 (0.012) dB	load interference	
	> 12.4 GHz to 18.0 GHz	< 0.043 (0.016) dB	correction	
	> 18.0 GHz to 26.5 GHz	< 0.043 (0.022) dB		
Interface to host	power supply	+5 V/0.1 A (USB low-power	er device)	
	remote control	as a USB device (function	) in full-speed mode,	
		compatible with USB 1.0/1	1.1/2.0 specifications	
	trigger input	differential (0 V/+3.3 V)		
	connector type	ODU Mini-Snap® L series,		
		six-pole cylindrical straight	t plug	
	permissible cable length	≤ 10 m (see also tables or		
Dimensions	W×H×L	48 mm × 50 mm × 250 mr	m	
		(1.89 in × 1.97 in × 9.84 in	1)	
	length including connecting cable	approx. 1.75 m (68.89 in)		
Weight		< 0.7 kg (1.54 lb)		



Block diagram of the R&S®NRP-Z27/-Z37 power sensor modules

## **Accessories for sensors**

## R&S®NRP-Z2 extension cables

Application		for extending the connection between an R&S®NRP-Zxx power sensor and the R&S®NRX base unit, another Rohde & Schwarz measuring instrument, an R&S®NRP-Z3/-Z4 USB adapter cable or an R&S®NRP-Z5 USB sensor hub		
Connectors	type	ODU Mini-Snap® L series, size 1, six-pole receptacle		
	sensor side			
	models .03/.05/.10	with in-line receptacle		
	model .15	with bulkhead receptacle for panel mounting		
		< 5 mm wall thickness		
	host side	straight plug		
Length	model .03	1.5 m		
	models .05/.15	3.5 m		
	model .10	8.5 m		
Permissible total length	including power sensor and R&S®NRX base unit or R&S®NRP-Z3/-Z4 USB adapter cable or R&S®NRP-Z5 USB sensor hub, if applicable	see tables below		

Supported combinations with R&S®NRX base unit or other Rohde & Schwarz measuring instruments with ODU Mini-Snap® receptacle (e.g. R&S®FSMR, R&S®SMA200A, R&S®SMF100A)

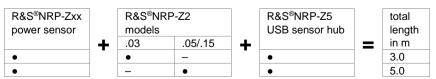
R&S®NRP-Zxx		R&S®NRF	&S®NRP-Z2 models			total	(shaded combination only
power sensor		.03	.05/.15	.10		length	supported by R&S®NRX
					_	in m	base unit; not permissible
•	+	•	_	_	=	3.0	for R&S®NRP-Z81/-Z85/-Z86
•		_	•	_		5.0	power sensors)
•		_	_	•		10.0	

Supported combinations with R&S®NRP-Z3/-Z4 USB adapter cables

R&S®NRP-Zxx power sensor		R&S®NRP-Z2 models			R&S®NRP-Z4 models			R&S®NRP-Z3/-Z4 model	total length	
		.03	.05/.15		.06	.04	.11	.02		in m
•		_	_		•	_	_	_		1.6
•		_	_		_	•	_	_		2.0
•		_	_	١.	_	_	•	_		2.5
•	+	_	_	+	_	_	_	•	=	3.5
•		•	_		_	_	_	•		5.0
•		_	•		•	_	_	_		5.1
•		_	•		_	•	_	_		5.5
•		_	•		_	_	•	_		6.0
•		_	•		_	_	_	•		7.0

(shaded combinations not permissible for R&S®NRP-Z81/-Z85/-Z86 power sensors)

Supported combinations with R&S®NRP-Z5 USB sensor hub (cable between sensor and hub)



Supported combinations with R&S®NRP-Z5 USB sensor hub (cable between hub and host)

R&S®NRP-Z5 USB sensor hub		R&S®NRP models	-Z2	R&S®NRP-Z4 models				standard USB cable (max. length: 5 m)		total length
		.03	.05/.15	.06	.04	.11	.02			in m
•		•	_		_		_	_		3.0
•		_	•		_		_	_		5.0
•	+	_	_	•	_	_	_	_	=	0.1
•		_	_	_	•	_	_	_		0.5
•		_	_	_	_	•	_	_		1.0
•		_	_	_	_	_	•	_		2.0
•		_	_	_	_	_	_	•		5.0

## R&S®NRP-Z3 active USB adapter cable

Application		for connecting an R&S®NRP-Zxx power sensor				
		to a USB host (PC or Rohde & Schwarz				
		measuring instrument with type A receptacle)				
Trigger input	maximum voltage	±15 V				
	logic level					
	low	< 0.8 V				
	high	> 2.0 V				
	input impedance	approx. 5 kΩ				
Connectors	sensor	ODU Mini-Snap® L series, size 1, six-pole				
		receptacle				
	USB host	USB type A plug				
Plug-in power supply	voltage/frequency	100 V to 240 V/50 Hz to 60 Hz				
	tolerance	±10 % for voltage, ±3 Hz for frequency				
	current consumption	25 mA (typ.) with sensor connected				
	connection	via adapter to all common AC supplies				
		(Europe, UK, USA, Australia)				
Dimensions (W × H × L)	USB adapter	48 mm × 45 mm × 140 mm				
		$(1.89 \text{ in} \times 1.77 \text{ in} \times 5.51 \text{ in})$				
	length including connecting cable	approx. 2 m (78.74 in)				
	plug-in power supply	52 mm × 73 mm × 110 mm				
		$(2.05 \text{ in} \times 2.87 \text{ in} \times 4.33 \text{ in})$				
	length of line to USB adapter	approx. 2 m (78.74 in)				
Weight	USB adapter	< 0.2 kg (0.44 lb)				
-	plug-in power supply	< 0.3 kg (0.66 lb)				

## R&S®NRP-Z4 passive USB adapter cable

Application		for connecting an R&S®NRP-Zxx power sensor			
		to a USB host (PC or Rohde & Schwarz			
		measuring instrument with type A receptacle)			
Connectors	sensor side	ODU Mini-Snap® L series, size 1, six-pole			
		receptacle			
	models .02/.04/.06	with in-line receptacle			
	model .11	with bulkhead receptacle for panel mounting			
		< 5 mm wall thickness			
	host side	USB type A plug			
Dimensions (length)	model .02	approx. 2 m (78.74 in)			
	model .04	approx. 0.5 m (19.69 in)			
	model .06	approx. 0.15 m (5.91 in)			
	model .11	approx. 1 m (39.37 in)			

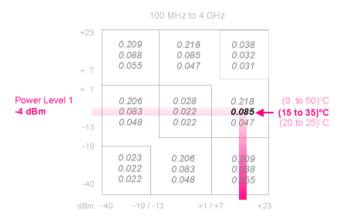
## R&S®NRP-Z5 USB sensor hub

Application		for connecting up to four R&S®NRP-Zxx power sensors to  • a USB host (PC or Rohde & Schwarz measuring instrument with type A receptacle)  • a Rohde & Schwarz measuring instrument (other than the R&S®NRX) with circular sensor connector (ODU Mini-Snap® L series, size 1, six-pole receptacle)		
Trigger input	maximum voltage	±8 V		
	logic level			
	low	< 0.8 V		
	high	> 2.0 V		
	input impedance	approx. 10 kΩ		
	minimum pulse width	35 ns (without R&S®NRP-Z2 extension cable)		
Trigger output	high-level output voltage	< 5.3 V (no load), > 2.0 V (50 Ω)		
	low-level output voltage	< 0.4 V at 5 mA sink current		
Power supply	voltage/power	12 V to 24 V (DC)/24 W		
	source	AC adapter supplied with the equipment or		
		equivalent DC voltage source		
		no supply from extra-low voltage supply systems		
		or via secondary cables > 30 m (98.43 ft)		
Connectors	sensors A to D	ODU Mini-Snap® L series, size 1, six-pole		
		receptacle		
	USB host	USB type B receptacle (certified USB 2.0 high-		
		speed cable supplied with the equipment)		
	for Rohde & Schwarz instrument	ODU Mini-Snap® L series, size 1, six-pole plug		
	trigger input, trigger output	BNC receptacle		
	power supply	receptacle for DC barrel connector,		
		$\varnothing$ 5.5 mm × $\varnothing$ 2.1 mm × 9.5 mm; inner		
		conductor is positive pole		
Dimensions (W × H × L)	sensor hub	140.6 mm × 36.6 mm × 138 mm		
		$(5.54 \text{ in} \times 1.44 \text{ in} \times 5.43 \text{ in})$		
Weight	excluding accessories	< 0.55 kg (1.21 lb)		
AC adapter	input voltage/frequency	100 V to 240 V/50 Hz to 60 Hz		
	tolerance	±10 % for voltage, ±3 Hz for frequency		
	input connector	C14 receptacle, in line with IEC 60320		
	output voltage/power	12 V (DC)/36 W		
	length of secondary cable	approx. 0.72 m (28.35 in) 120 mm × 52 mm × 31 mm		
	dimensions (W x H x L)			
		(4.72 in × 2.05 in × 1.22 in)		
	weight	< 0.3 kg (0.66 lb)		

## **Appendix**

# Reading the uncertainty of diode power sensors for relative power measurements

The example shows a level step of approx. 14 dB (-4 dBm  $\rightarrow$  +10 dBm) at 1.9 GHz and an ambient temperature of +28 °C for an R&S $^{\circ}$ NRP-Z21 power sensor.



Power Level 2: +10 dBm

## **Ordering information**

Designation	Туре	Order No.
Two-path diode power sensors		·
1 nW to 100 mW, 10 MHz to 8 GHz	R&S®NRP-Z211	1417.0409.02
1 nW to 100 mW, 10 MHz to 18 GHz	R&S®NRP-Z221	1417.0309.02
Wideband power sensors		·
1 nW to 100 mW, 50 MHz to 18 GHz	R&S®NRP-Z81	1137.9009.02
1 nW to 100 mW, 50 MHz to 40 GHz (2.92 mm)	R&S®NRP-Z85	1411.7501.02
1 nW to 100 mW, 50 MHz to 40 GHz (2.40 mm)	R&S®NRP-Z86	1417.0109.40
1 nW to 100 mW, 50 MHz to 44 GHz (2.40 mm)	R&S®NRP-Z86	1417.0109.44
Level control sensors	<u>'</u>	
200 pW to 100 mW, 9 kHz to 6 GHz	R&S®NRP-Z98	1170.8508.02
200 pW to 100 mW, 10 MHz to 18 GHz	R&S®NRP-Z28	1170.8008.02
Power sensor modules	<u>'</u>	
4 μW to 400 mW, DC to 18 GHz	R&S®NRP-Z27	1169.4102.02
4 μW to 400 mW, DC to 26.5 GHz	R&S®NRP-Z37	1169.3206.02
Recommended extras	<u>'</u>	
R&S®NRPV virtual power meter (PC application),	R&S®NRPZ-K1	1418.9800.03
activation for one R&S®NRP-Zxx power sensor		
Sensor extension cable to 3 m	R&S®NRP-Z2	1146.6750.03
Sensor extension cable to 5 m	R&S®NRP-Z2	1146.6750.05
Sensor extension cable to 10 m	R&S®NRP-Z2	1146.6750.10
Sensor extension cable to 5 m	R&S®NRP-Z2	1146.6750.15
(with bulkhead receptacle for panel mounting)		
USB adapter cable (active)	R&S®NRP-Z3	1146.7005.02
USB adapter cable (passive, length: 2.0 m)	R&S®NRP-Z4	1146.8001.02
USB adapter cable (passive, length: 0.5 m)	R&S®NRP-Z4	1146.8001.04
USB adapter cable (passive, length: 0.15 m)	R&S®NRP-Z4	1146.8001.06
USB adapter cable (passive, length: 1.0 m, with bulkhead receptacle for	R&S®NRP-Z4	1146.8001.11
panel mounting)		
USB sensor hub	R&S®NRP-Z5	1146.7740.02

Warranty		
R&S®NRX base unit, power sensors and R&S®NRP-Z5	3 years	
All other items <sup>45</sup>	1 year	
Options		
Extended warranty, one year	R&S®WE1	Please contact your local
Extended warranty, two years	R&S®WE2	Rohde & Schwarz sales
Extended warranty with calibration coverage, one year	R&S®CW1	office.
Extended warranty with calibration coverage, two years	R&S®CW2	
Extended warranty with accredited calibration coverage, one year	R&S®AW1	
Extended warranty with accredited calibration coverage, two years	R&S®AW2	

#### Extended warranty with a term of one and two years (WE1 and WE2)

Repairs carried out during the contract term are free of charge <sup>46</sup>. Necessary calibration and adjustments carried out during repairs are also covered.

#### Extended warranty with calibration (CW1 and CW2)

Enhance your extended warranty by adding calibration coverage at a package price. This package ensures that your Rohde & Schwarz product is regularly calibrated, inspected and maintained during the term of the contract. It includes all repairs <sup>46</sup> and calibration at the recommended intervals as well as any calibration carried out during repairs or option upgrades.

#### Extended warranty with accredited calibration (AW1 and AW2)

Enhance your extended warranty by adding accredited calibration coverage at a package price. This package ensures that your Rohde & Schwarz product is regularly calibrated under accreditation, inspected and maintained during the term of the contract. It includes all repairs <sup>46</sup> and accredited calibration at the recommended intervals as well as any accredited calibration carried out during repairs or option upgrades.

## **Endnotes**

<sup>1</sup> Specifications apply to timeslots/gates with a duration of 12.5 % referenced to the signal period (duty cycle 1:8). For other waveforms, the following equation applies: lower measurement limit = lower measurement limit for continuous average mode / √(duty cycle).

<sup>2</sup> With a resolution of 256 pixels.

3 Specifications apply to the default transition setting of 0 dB. The transition regions can be shifted by as much as -20 dB using an adequate offset.

<sup>4</sup> To prevent aliasing in the case of signals with discrete modulation frequencies between 100 kHz and 1 MHz.

<sup>5</sup> Time span prior to triggering, where the trigger signal must be entirely below the threshold level in the case of a positive slope and vice versa in the case of a negative slope.

<sup>6</sup> Specifications expressed as an expanded uncertainty with a confidence level of 95 % (two standard deviations). For calculating zero offsets at higher confidence levels, use the properties of the normal distribution (e.g. 99.7 % confidence level for three standard deviations).

<sup>7</sup> Specifications apply to zeroing with a duration of 4 s. Zeroing for more than 4 s lowers uncertainty correspondingly (half values for 16 s).

<sup>8</sup> Within one hour after zeroing, permissible temperature change ±1 °C, following a two-hour warm-up of the power sensor.

<sup>9</sup> Two standard deviations at 10.24 s integration time in continuous average mode, with aperture time set to default value. The integration time is defined as the total time used for signal acquisition, i.e. the product of twice the aperture time and the averaging number. Multiplying the noise specifications by √(10.24 s/integration time) yields the noise contribution at other integration times. Using a von Hann window function increases noise by a factor of 1.22.

Expanded uncertainty (k = 2) for absolute power measurements on CW signals with automatic path selection and the default transition setting of 0 dB. Specifications include calibration uncertainty, linearity and temperature effect. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. As a rule of thumb, the contribution of zero offset can be neglected for power levels above –30 dBm for the R&S®NRP-Z211/-Z221. The contribution of measurement noise depends on power and integration time and can be neglected below 0.01 dB.

Example: The uncertainty of a power measurement at 3.2 nW (–55 dBm) and 1.9 GHz is to be determined for an R&S®NRP-Z11. The ambient temperature is +29 °C and the averaging number is set to 32 in the continuous average mode with an aperture time of 20 ms.

Since path 1 is used for the measurement, the typical absolute uncertainty due to zero offset is 64 pW (typical) after external zeroing, which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{3.2 \, nW + 64 \, pW}{3.2 \, nW} = 0.086 \, dB$$

Using the formula in endnote 9, the absolute noise contribution of path 1 is typically 40 pW  $\times \sqrt{(10.24 \text{ s/}(32 \times 2 \times 0.02 \text{ s}))} = 113 \text{ pW}$ , which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{3.2 \, nW + 113 \, pW}{3.2 \, nW} = 0.151 \, dB$$

Combined with the uncertainty of 0.081 dB for absolute power measurements under the given conditions, the total expanded uncertainty is

$$\sqrt{0.086^2 + 0.151^2 + 0.081^2} dB = 0.192 dB$$
.

The contribution of zero drift has been neglected in this case. It must be treated like zero offset if it is relevant for total uncertainty.

11 Expanded uncertainty (k = 2) for relative power measurements on CW signals of the same frequency with automatic path selection and a default transition setting of 0 dB. For reading the measurement uncertainty diagrams of universal, average and level control sensors, see the Appendix.

Specifications include calibration uncertainty (only if different paths are affected), linearity and temperature effect. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. As a rule of thumb, the contribution of zero offset can be neglected for power levels above –30 dBm for the R&S®NRP-Z211/-Z221. The contribution of measurement noise depends on power and integration time and can be neglected below 0.01 dB.

Example: The uncertainty of a power step from 1 mW (0 dBm) to 10 nW (-50 dBm) at 5.4 GHz is to be determined for an R&S®NRP-Z11. The ambient temperature is +20 °C and the averaging number is set to 16 for both measurements in the continuous average mode with an aperture time of 20 ms. For the calculation of total uncertainty, the relative contribution of noise, zero offset and zero drift must be taken into account for both measurements. In this example, all contributions at 0 dBm and the effect of zero drift have been neolected.

Since path 1 is used for the -50 dBm measurement, the typical absolute uncertainty due to zero offset is 64 pW after external zeroing, which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{10 \, nW \, + \, 64 \, pW}{10 \, nW} = 0.028 \, dB$$

Using the formula in endnote 9, the absolute noise contribution of path 1 is typically 40 pW  $\times \sqrt{(10.24 \text{ s}/(16 \times 2 \times 0.02 \text{ s}))}$  = 160 pW, which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{10 \text{ nW} + 160 \text{ pW}}{10 \text{ nW}} = 0.069 \text{ dB}$$

Combined with the uncertainty of 0.054 dB for relative power measurements under the given conditions, the total expanded uncertainty is

$$\sqrt{0.028^2 + 0.069^2 + 0.054^2} dB = 0.092 dB$$

12 Gamma correction activated.

<sup>13</sup> Preceding sensor section (nominal value).

14 Preferably used with determined modulation when the aperture time cannot be matched to the modulation period. Compared to a uniform window, measurement noise is about 22 % higher.

<sup>15</sup> For measuring the power of periodic bursts based on an average power measurement.

- To increase measurement speed, the power sensor can be operated in buffered mode. In this mode, measurement results are stored in a buffer of user-definable size and then output as a block of data when the buffer is full. To enhance measurement speed even further, the sensor can be set to record the entire series of measurements when triggered by a single event. In this case, the power sensor automatically starts a new measurement as soon as it has completed the previous one.
- 17 This parameter enables power measurements on modulated bursts. The parameter must be longer in duration than modulation-induced power drops within the burst.
- <sup>18</sup> To exclude unwanted portions of the signal from the measurement result.
- <sup>19</sup> Valid for Repeat mode, extending from the beginning to the end of all transfers via the USB interface of the power sensor. Measurement times under remote control of the R&S®NRX base unit via IEC/IEEE bus are approximately 2.5 ms longer, extending from the start of the measurement up to when the measurement result has been supplied to the output buffer of the R&S®NRX.
- 20 Integration time is defined as the total time used for signal acquisition, i.e. taking into account the chosen aperture/acquisition time and the averaging
- Magnitude of measurement error referenced to an ideal thermal power sensor that measures the sum power of carrier and harmonics. For the R&S®NRP-Z211/-Z221, specifications apply to automatic path selection and power levels up to +16 dBm or, within a subrange, to 0.1 mW (-10 dBm) for path 1 and 40 mW (+16 dBm) for path 2. Above the mentioned power limit, specifications must be raised by a factor of 1.25 per 1 dB rise in power level. Within a subrange, measurement errors are proportional to the measured power in W.
- 22 Measurement error referenced to a CW signal of equal power and frequency. For the R&S®NRP-Z211/-Z221, specifications apply to automatic path selection and power levels up to +16 dBm or, within a subrange, to 0.1 mW (-10 dBm) for path 1 and 39.8 mW (+16 dBm) for path 2 Above the mentioned power limit, specifications must be raised by a factor of 1.25 per 1 dB rise in power level. Within a subrange, measurement errors are proportional to the measured power in W.
- <sup>23</sup> Applies to the R&S®NRP-Z211/-Z221, referenced to 0 dBm.
- <sup>24</sup> Expanded uncertainty (k = 2) for absolute power measurements on CW signals at the calibration level within a temperature range from +20 °C to +25 °C and at the calibration frequencies (10 MHz, 15 MHz, 20 MHz, 30 MHz, 50 MHz, 100 MHz; in steps of 250 MHz from 250 MHz to the upper frequency limit). Specifications include zero offset and measurement noise (up to a 2σ value of 0.004 dB). The calibration level for the R&S®NRP-Z211/-Z221 is -10 dBm for paths 1 and 2.
- <sup>25</sup> With full video bandwidth. Reduce the specified minimum levels according to the reduction of sampling noise at lower bandwidths.
- 26 Specifications are valid from +15 °C to +50 °C ambient temperature. Below +15 °C, video bandwidth and single-shot bandwidth continuously decrease down to 20 MHz (typical) at 0 °C. Accordingly, the sensor rise time increases up to 50 ns for signals below 500 MHz and up to 20 ns for higher frequencies (typical at 0 °C).
- Specifications are valid at +23 °C ambient temperature for power levels ≤ -20 dBm and frequencies ≥ 500 MHz. For measurements at other temperatures levels and/or frequencies, use the multipliers from table A.
- Measured over a one-minute interval, at constant temperature, two standard deviations.
- 29 512k averages taken with the aperture time set to default (10 μs). The measurement noise with other averaging numbers can be calculated by applying the multipliers indicated below:

Averaging number	512k	128k	32k	8k	2k	512	128	32	8
Integration time	10.49 s	2.62 s	655.36 ms	163.84 ms	40.96 ms	10.24 ms	2.56 ms	0.64 ms	0.16 ms
Noise multiplier	1	2	4	8	16	32	64	128	256

Using a von Hann window function further increases noise by a factor of 1.22. Integration time is defined as the total time used for signal acquisition, i.e. the product of twice the aperture time and the averaging number.

The measurement noise is always minimal for the default aperture time. Increasing the aperture time above this value is only useful for suppressing modulation-induced fluctuations of the measurement result, e.g. by matching the aperture time to the modulation period.

Expanded uncertainty (k = 2) for absolute power measurements on CW signals. Specifications include calibration uncertainty, linearity, influence of sensor-induced harmonics reflected on the DUT, and temperature effect. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. As a rule of thumb, the contribution of zero offset and zero drift can be neglected for power levels above –35 dBm if external zeroing has been applied. The contribution of measurement noise can be neglected below 0.02 dB.

Example: The power to be measured is 40 nW (-44 dBm) at 12 GHz in the continuous average mode; ambient temperature +35 °C; averaging number set to 32k with an aperture time of 10 µs (1 s integration time).

The typical absolute uncertainty due to zero offset is 220 pW at +23 °C. From table A, a multiplier of 1.4 can be taken to read a typical zero offset of 308 pW at +35 °C. The corresponding relative measurement uncertainty can be calculated as follows:

$$10 \times lg \frac{40 \text{ nW} + 308 \text{ pW}}{40 \text{ nW}} = 0.033 \text{ dB}$$

Using the noise multiplier (4) from endnote 29 and the multiplier (1.4) from table A, the absolute noise contribution is typically 110 pW  $\times$  4  $\times$  1.4 = 616 pW, which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{40 \, nW + 616 \, pW}{40 \, nW} = 0.066 \, dB$$

Combined with the value of 0.18 dB specified for the uncertainty of absolute power measurements at 12 GHz, the total expanded uncertainty is

$$\sqrt{0.18^2 + 0.033^2 + 0.066^2} dB = 0.195 dB$$

The contribution of zero drift has been neglected in this case. It must be treated like zero offset if it is relevant for total uncertainty.

31 Expanded uncertainty (k = 2) for relative power measurements on CW signals of the same frequency, carried out using a matched source. For reading the measurement uncertainty, see the Appendix. For small power ratios up to 5 dB, expanded uncertainty will typically not exceed 0.06 dB (0.08 dB) at +23°C (from 0°C to +50°C).

Specifications include linearity of the sensor, influence of sensor-induced harmonics that may be re-reflected at the source (DUT), and temperature effect. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. As a rule of thumb, the contribution of zero offset and zero drift can be neglected for power levels above –35 dBm if external zeroing has been applied. The contribution of measurement noise can be neglected below a two-sigma value of 0.02 dB. A source (DUT) SWR of 3 has been assumed for signal frequency harmonics emanating from the sensor.

Example: The uncertainty of a power step from 1 mW (0 dBm) to 1  $\mu$ W (-30 dBm) at 31 GHz is to be determined with an R&S®NRP-Z85. The ambient temperature is +21  $^{\circ}$ C and the averaging number is set to 128 for both measurements. Measurements are carried out in the continuous average mode with a default aperture time of 10  $\mu$ s.

For the calculation of total uncertainty, the relative contribution of zero offset and zero drift can be neglected in this case since both power levels are higher than -30 dBm. Noise must be taken into account for measurements at 1  $\mu$ W. Using the noise multiplier (64) from endnote 29 and the multiplier (1.0) from table A, the absolute noise contribution is typically 110 pW × 64 × 1.0 = 7 nW, which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{1 \mu W + 0.007 \, nW}{1 \, \mu W} = 0.030 \, dB$$

Combined with the uncertainty of 0.126 dB for relative power measurements with a matched source (see table), total expanded uncertainty is

$$\sqrt{0.03^2 + 0.126^2} dB = 0.130 dB$$

Mismatch of the source (DUT) at the signal frequency can further impair linearity due to a change of the input reflection coefficient of the power sensor as a function of applied power (for specifications of reflection coefficient changes, see page 13). Limits of the induced linearity error can be approximated by

$$\pm\,8.7~\mathrm{dB}\cdot r_{\mathrm{DUT}}\,\cdot\Delta r_{\mathrm{SEN}}$$

where  $r_{\text{DUT}}$  denotes the magnitude of the reflection coefficient of the source (DUT) and  $\Delta r_{\text{SEN}}$  denotes the change of the input reflection coefficient of the power sensor.

- 32 Magnitude of measurement error referenced to an ideal thermal power sensor that measures the sum power of carrier and harmonics. For power levels below −10 dBm, the specifications for 2 × f₀ (3 × f₀) can be lowered by a factor of √10 (10) per 10 dB below −10 dBm. Example: At 12 GHz/–30 dBm, the influence of the second harmonic, suppressed by 20 dBc, will cause an error of max. 0.25 dB ÷ 10 = 0.025 dB. Standard uncertainties can be assumed to be half the values.
- 33 Magnitude of the change vector in the complex plane.
- <sup>34</sup> Expanded uncertainty (k = 2) for absolute power measurements on CW signals at the calibration level (–10 dBm) within a temperature range from +20 °C to +25 °C and at the calibration frequencies (50/55/60/68/80/100/200/300/400/499.99/500/600/720/850/1000/1500 MHz; R&S®NRP-Z81: in steps of 0.5 GHz from 2 GHz to the upper frequency limit; R&S®NRP-Z85/-Z86: in steps of 1 GHz from 2 GHz to 26 GHz and in steps of 0.5 GHz from 26.5 GHz to 44 GHz). Specifications include zero offset and measurement noise (up to a 2σ value of 0.01 dB).
- 35 Equivalent source SWR.
- <sup>36</sup> Between RF input and RF output (test port).
- <sup>37</sup> With activated auto delay, the beginning of a measurement sequence is delayed so that settled readings are obtained even if the measurement command (remote trigger) coincides with a signal step up to ±10 dB.
- Expanded uncertainty (k = 2) for absolute power measurements up to 100 mW (+20 dBm) at the calibration frequencies (see endnote 40). Specifications include calibration uncertainty, linearity, temperature effect and interference from the wave reflected by the load on the RF output. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. If the measured power exceeds 100 mW, the power coefficient of the integrated power splitter must be taken into account (see endnote 43). As a rule of thumb, the contribution of zero offset can be neglected for power levels above –7 dBm if external zeroing has been applied. The contribution of measurement noise can be neglected below 0.01 dB.

Example: The power to be measured with an R&S®NRP-Z37 is 50  $\mu$ W (–13 dBm) at 19 GHz; ambient temperature +29  $^{\circ}$ C; averaging number set to 64 in continuous average mode with an aperture time of 20 ms.

The maximum absolute uncertainty due to zero offset (after external zeroing) is 400 nW, which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{50 \,\mu W + \,400 \,nW}{50 \,\mu W} = 0.035 \,dB$$

Using the formula in endnote 9, the maximum absolute noise contribution is 240 nW  $\times \sqrt{(10.24 \text{ s}/(64 \times 2 \times 0.02 \text{ s}))} = 480 \text{ nW}$ , which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{50 \,\mu W + 480 \,nW}{50 \,\mu W} = 0.042 \,dB$$

Combined with the value of 0.137 dB specified for the uncertainty of absolute power measurements, the total expanded uncertainty is

$$\sqrt{0.035^2 + 0.042^2 + 0.137^2} dB = 0.148 dB$$

- Expanded uncertainty (k = 2) for relative power measurements on CW signals of the same frequency. Specifications include linearity and temperature effect. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. As a rule of thumb, the contribution of zero offset can be neglected for power levels above –7 dBm if external zeroing has been applied. The contribution of measurement noise can be neglected below 0.01 dB. See also the example in endnote 9 for taking into account zero offset and noise with relative measurements.
- <sup>40</sup> Expanded uncertainty (k = 2) for absolute power measurements at the calibration level (0 dBm) within a temperature range from +20 °C to +25 °C and at the calibration frequencies. Specifications include zero offset and measurement noise (up to a 2σ value of 0.004 dB). The load on the RF signal output must be of a low-reflection type (SWR < 1.05) or load interference correction must be applied.</p>

Calibration frequencies: 0.1/0.5/1/3/5/10/50/100 MHz; in steps of 100 MHz from 100 MHz to the upper frequency limit.

- <sup>41</sup> Error of an absolute power measurement with respect to temperature, taking into account the power sensor section, the power splitter and the RF cable (temperature-dependent interference from the load on the RF signal output due to phase change).
- <sup>42</sup> Expanded uncertainty for relative power measurements on CW signals of the same frequency, referenced to the calibration level (0 dBm) and excluding zero offset, zero drift and measurement noise.
- 43 Maximum change of insertion loss of the power splitter with respect to input power, leading to an equivalent measurement error of the power sensor module and a change of the power available at the RF signal output. The power coefficient should be taken into account if the input power exceeds 100 mW (+20 dBm).
- <sup>44</sup> Measurement error due to interference of the wave reflected by a mismatched load on the RF signal output. Specifications are indicated for a 0.1 reflection coefficient of the load. Since the load interference error is proportional to the amplitude of the reflected wave, half (twice) the values will be encountered for a reflection coefficient of 0.05 (0.2). The error introduced by an R&S®FSMR26 at the RF signal output does not exceed ±0.06 dB from DC to 2 GHz, ±0.10 dB up to 18 GHz, and ±0.14 dB up to 26.5 GHz.
  - Values in ( ) represent residual error contribution after numeric load interference correction. This correction function requires the complex reflection coefficient of the load to be transferred to the power sensor module. The residual error contribution of an R&S®FSMR26 at the RF signal output does not exceed ±0.003 dB from DC to 2 GHz, ±0.04 dB up to 18 GHz, and ±0.07 dB up to 26.5 GHz.
- <sup>45</sup> For options that are installed, the remaining base unit warranty applies if longer than 1 year. Exception: all batteries have a 1 year warranty.
- <sup>46</sup> Excluding defects caused by incorrect operation or handling and force majeure. Wear-and-tear parts are not included.

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## Regional contact

- Europe, Africa, Middle East | +49 89 4129 12345 customersupport@rohde-schwarz.com
- North America | 1 888 TEST RSA (1 888 837 87 72) customer.support@rsa.rohde-schwarz.com
- Latin America | +1 410 910 79 88 customersupport.la@rohde-schwarz.com
- Asia Pacific | +65 65 13 04 88 customersupport.asia@rohde-schwarz.com
- China | +86 800 810 82 28 | +86 400 650 58 96 customersupport.china@rohde-schwarz.com



